



PROGRAMME OF
THE EUROPEAN UNION



IMPLEMENTED BY



EUMETSAT



JOINT TRAINING IN ATMOSPHERIC COMPOSITION

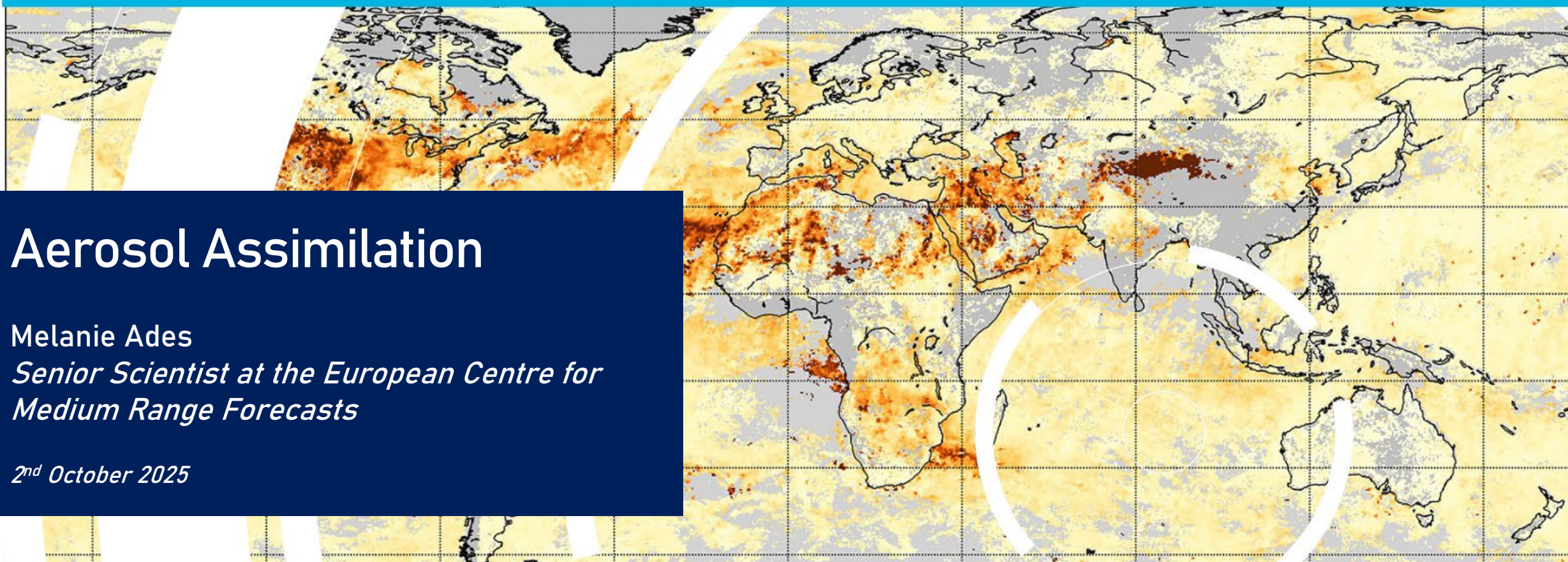
13 -17 OCTOBER 2025, BRUSSELS

Aerosol Assimilation

Melanie Ades

*Senior Scientist at the European Centre for
Medium Range Forecasts*

2nd October 2025

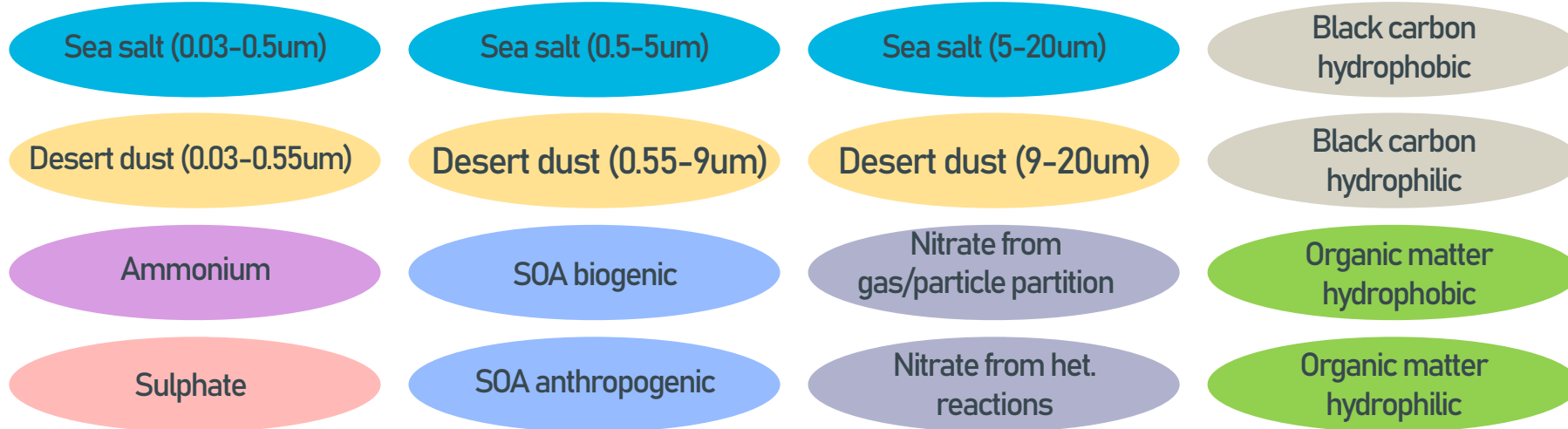






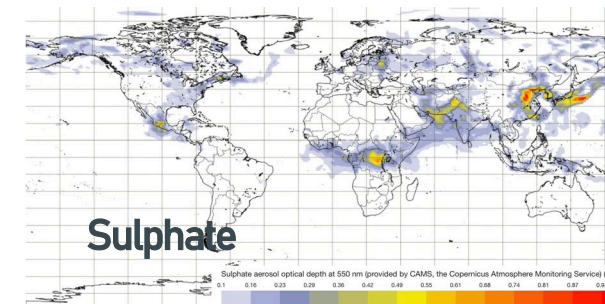
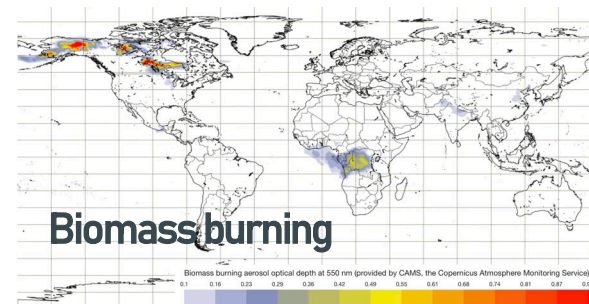
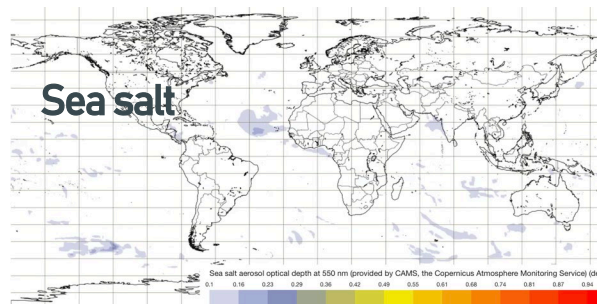
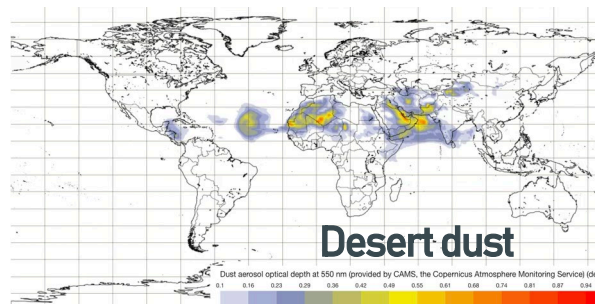
CAMS Aerosol model

copernicus.eumetsat.int



See Samuel Remy lecture

- CAMS uses a bin/bulk aerosol scheme to model the transport, emission and deposition of small particles/aerosols
- 16 different tracers are used to represent 8 different aerosol species
- Each type of aerosol has bespoke processes modelling how that aerosol behaves in the model: emission, deposition, sedimentation, chemical reactions
- Coupled to chemistry via sulphate, nitrate and ammonium and via aerosol input to the CB05 chemical scheme



Aerosol optical depth at 550nm valid for Tuesday 8th July 2025, 3 UTC



Data Assimilation

What is it and how does it work for aerosols?

Challenges of DA for aerosols

Correcting different species height profiles of aerosols

Emission inversions for aerosols

Can we use satellite aerosol observations to correct emissions?

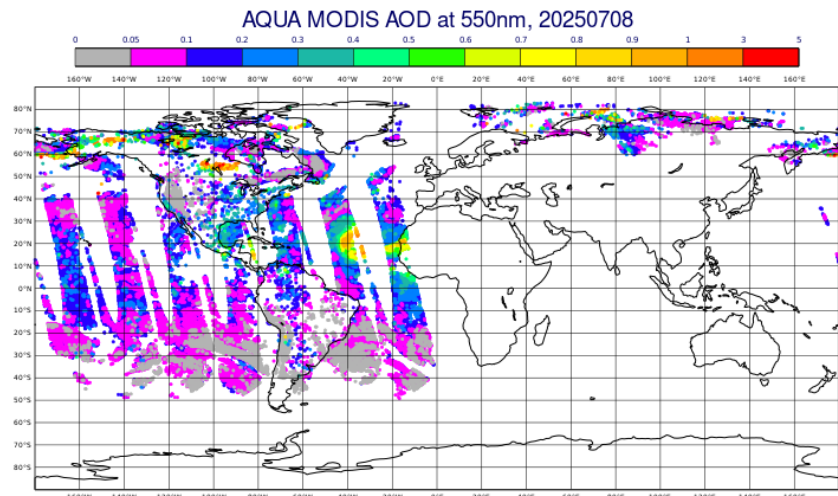
CAMS aerosol applications

How are the aerosol forecasts used?



Data Assimilation: what is it?

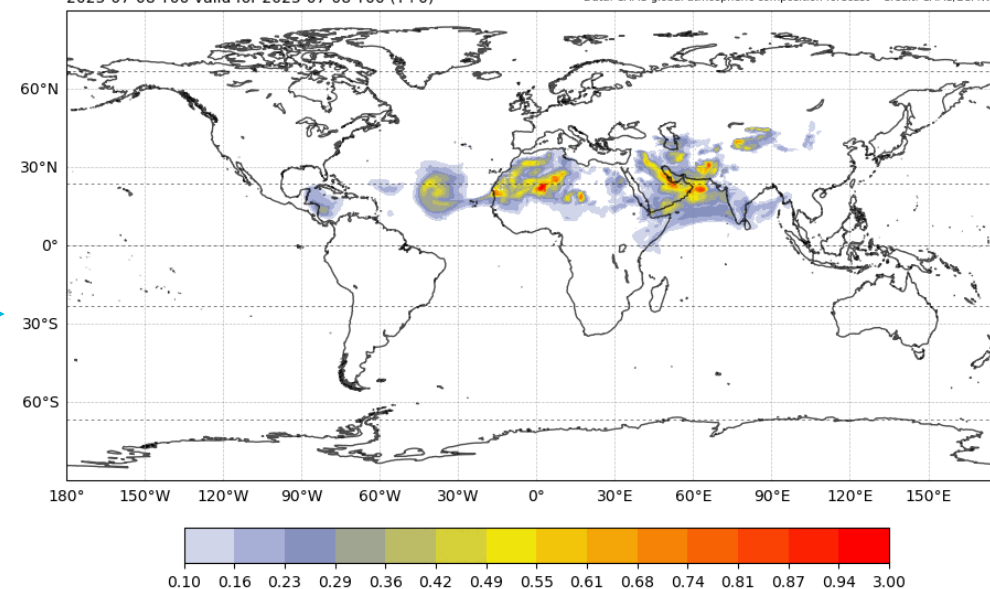
copernicus.eumetsat.int



Satellite observations

CAMS Forecast Dust Aerosol Optical Depth at 550nm

2025-07-08 T00 valid for 2025-07-08 T00 (T+0) Data: CAMS global atmospheric composition forecast • Credit: CAMS/ECMWF



Medium-range forecast

Forecast

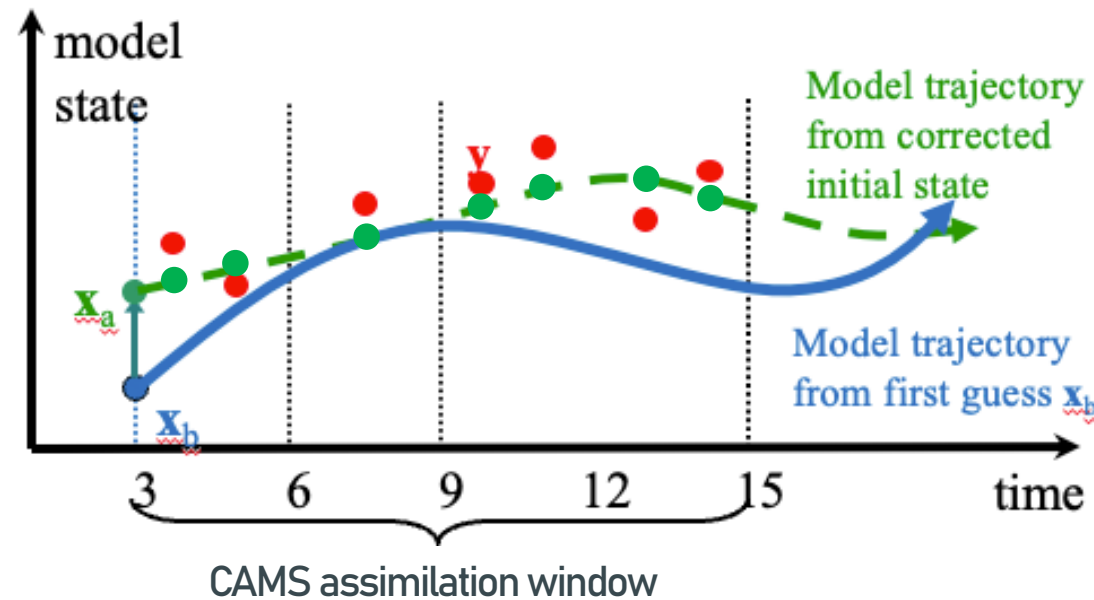
Analysis

Forecast

Analysis

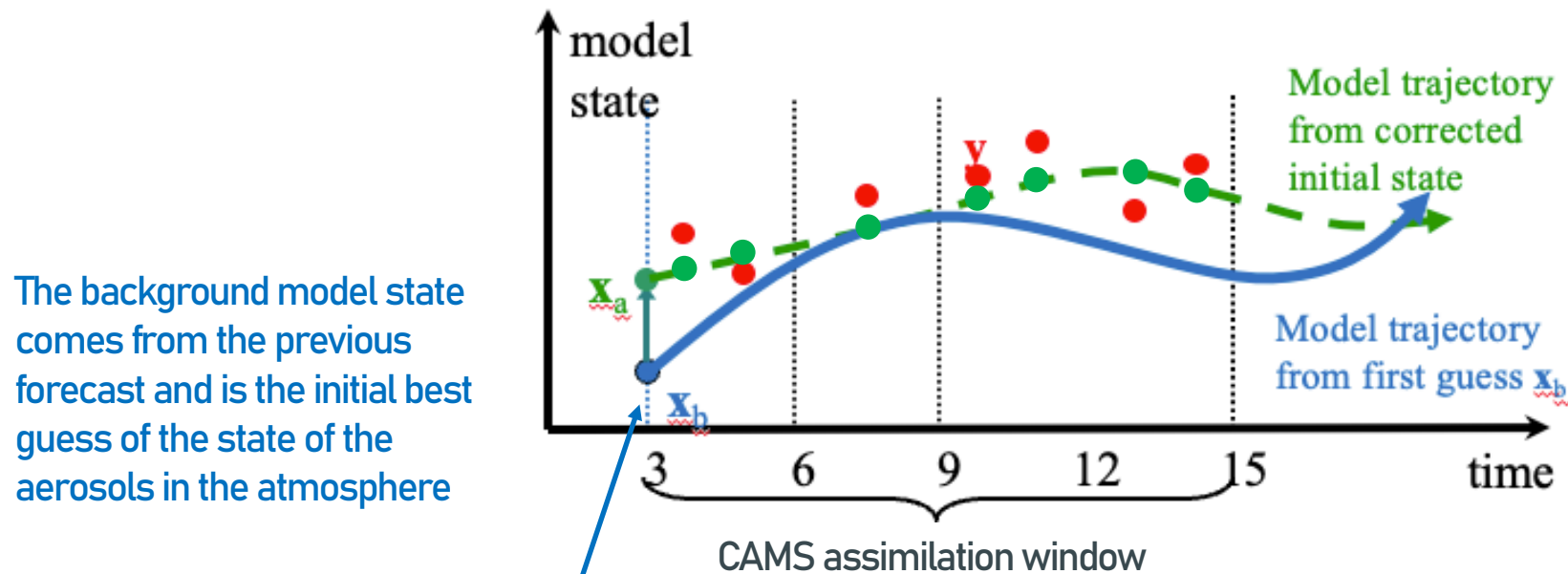
Yesterday's forecast is adjusted by today's observations to produce the outlook for tomorrow. Every day.

- NWP definition: Combining data and model in an 'optimal' way to produce the best possible initial conditions for a numerical forecast
- Optimal in a statistical sense: minimize error and/or maximize probability of the analysis being correct
- Many different methods exist for solving this problem; ENKF, En-4D-Var, EnVar, 3D-Var, 4D-Var
- CAMS uses ECMWF's 4-dimensional variational data assimilation system or 4D-Var with a 12-h window



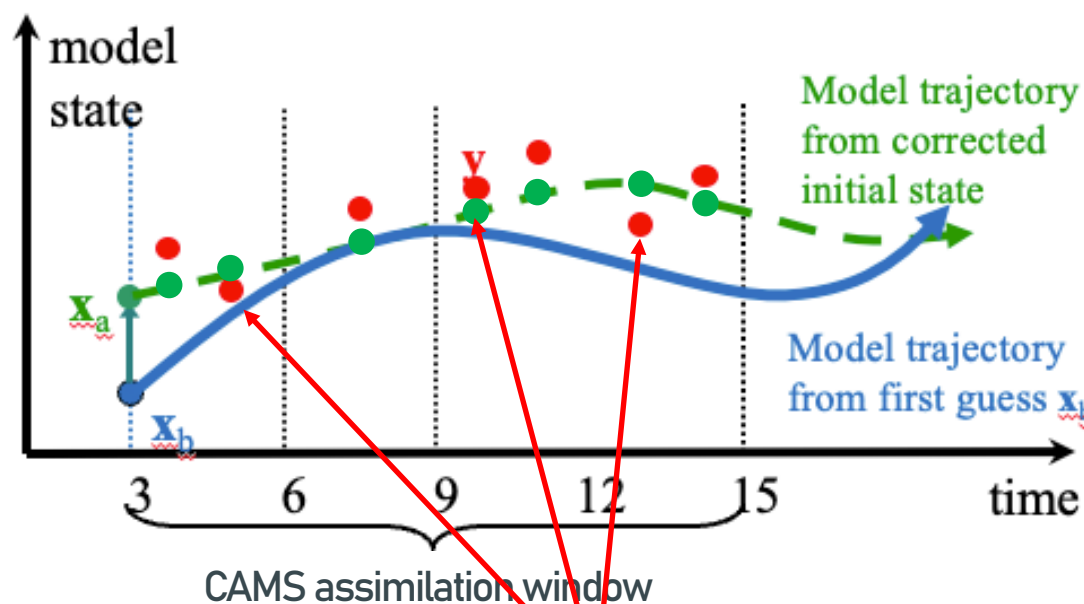
$$J(\mathbf{x}) = (\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + \sum_{i=0}^n (\mathbf{y}_i - H_i[\mathbf{x}_i])^T \mathbf{R}_i^{-1} (\mathbf{y}_i - H_i[\mathbf{x}_i])$$

- NWP definition: Combining data and model in an 'optimal' way to produce the best possible initial conditions for a numerical forecast
- Optimal in a statistical sense: minimize error and/or maximize probability of the analysis being correct
- Many different methods exist for solving this problem; ENKF, En-4D-Var, EnVar, 3D-Var, 4D-Var
- CAMS uses ECMWF's 4-dimensional variational data assimilation system or 4D-Var with a 12-h window



$$J(x) = (x - x_b)^T B^{-1} (x - x_b) + \sum_{i=0}^n (y_i - H_i[x_i])^T R_i^{-1} (y_i - H_i[x_i])$$

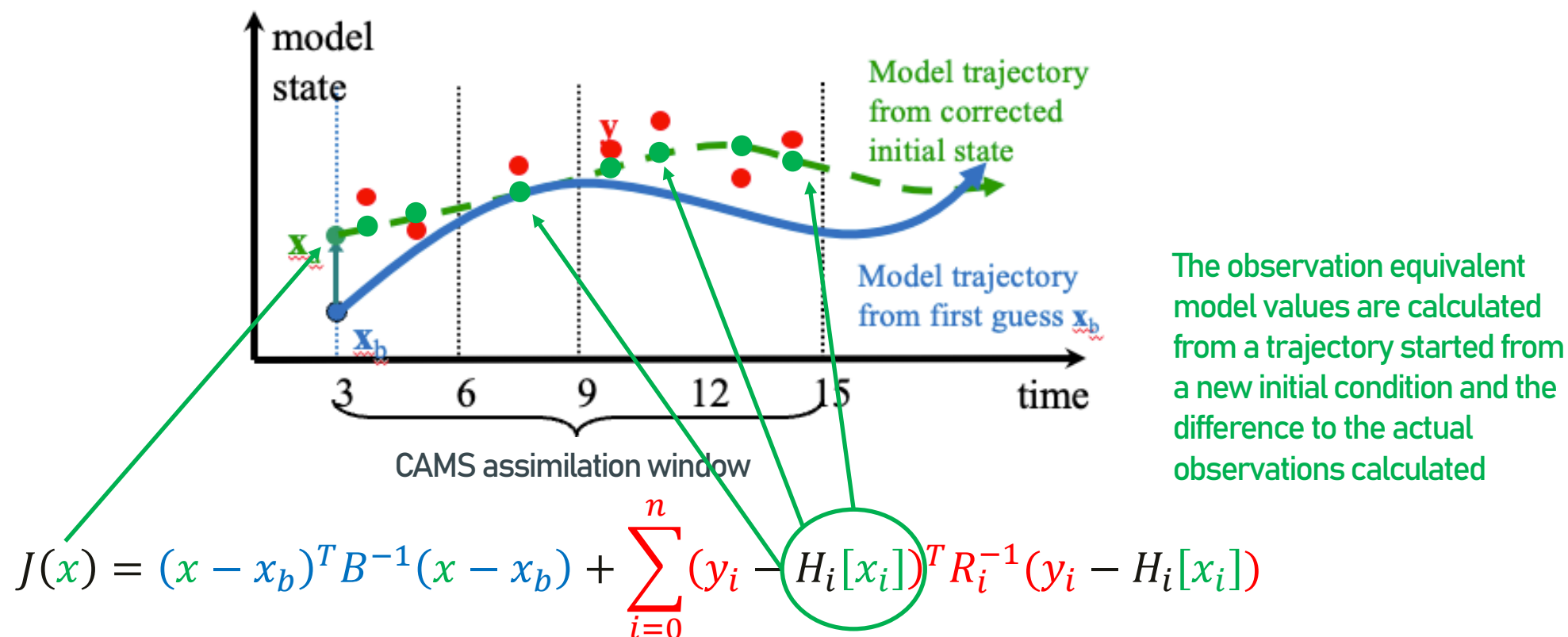
- NWP definition: Combining data and model in an 'optimal' way to produce the best possible initial conditions for a numerical forecast
- Optimal in a statistical sense: minimize error and/or maximize probability of the analysis being correct
- Many different methods exist for solving this problem; ENKF, En-4D-Var, EnVar, 3D-Var, 4D-Var
- CAMS uses ECMWF's 4-dimensional variational data assimilation system or 4D-Var with a 12-h window



The observations for aerosols come from satellites in the CAMS system and are of Aerosol Optical Depth

$$J(x) = (x - x_b)^T B^{-1} (x - x_b) + \sum_{i=0}^n (y_i - H_i[x_i])^T R_i^{-1} (y_i - H_i[x_i])$$

- NWP definition: Combining data and model in an 'optimal' way to produce the best possible initial conditions for a numerical forecast
- Optimal in a statistical sense: minimize error and/or maximize probability of the analysis being correct
- Many different methods exist for solving this problem; ENKF, En-4D-Var, EnVar, 3D-Var, 4D-Var
- CAMS uses ECMWF's 4-dimensional variational data assimilation system or 4D-Var with a 12-h window



$$J(x) = (x - x_b)^T B^{-1} (x - x_b) + \sum_{i=0}^n (y_i - H_i[x_i])^T R_i^{-1} (y_i - H_i[x_i])$$

x : control vector

x_b : model background (short forecast)

B : background error covariance matrix

y : observations

$H[x]$: Model equivalent of observations

R : Observation error covariance matrix

NWP

vorticity
divergence
temperature
surface pressure (logarithm)
specific humidity

Atmospheric Composition

aerosol mixing ratio

ozone
carbon monoxide
nitrogen dioxide
formaldehyde
sulphur dioxide
carbon dioxide
methane

AC control variables mainly treated as passive tracers when minimising the cost function. No emission, deposition or chemical reactions are modelled.

$$J(x) = (x - x_b)^T B^{-1} (x - x_b) + \sum_{i=0}^n (y_i - H_i[x_i])^T R_i^{-1} (y_i - H_i[x_i])$$

Observation operator H maps model state at beginning of the assimilation window (t=0) to the observation time and location

Direct assimilation of radiance observations:

The observation operator must incorporate an additional step to compute radiances from the model state variables (radiative transfer model, e.g. RTTOV)

CAMS is starting to explore this in the HE CAMEO project

Assimilation of retrievals:

Good characterization of retrieval is crucial:

- Averaging kernels
- A priori
- Error estimates
- Quality flags

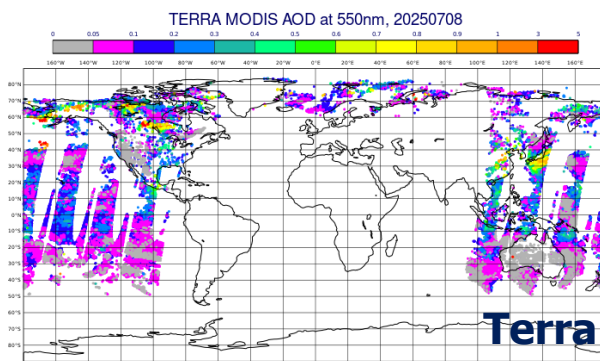
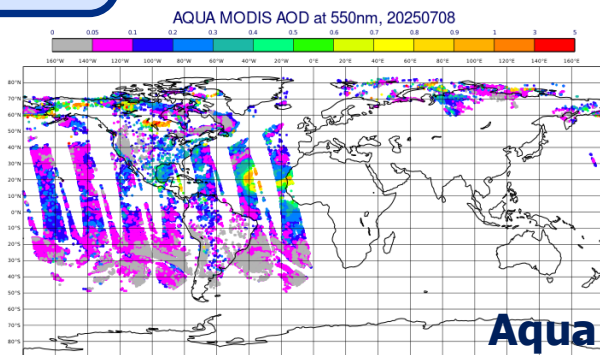
CAMS currently assimilates retrievals of Aerosol Optical Depth



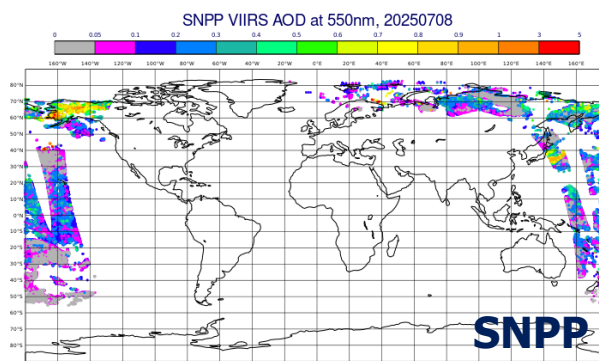
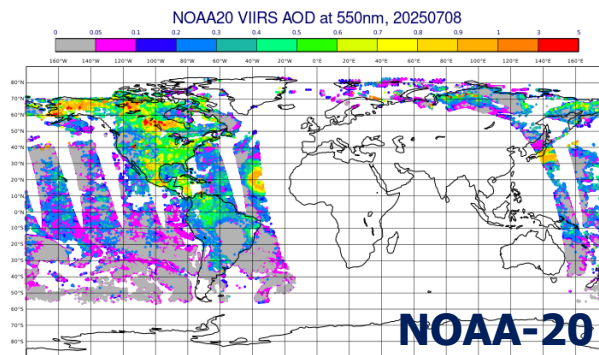
Aerosol observations used

γ_i

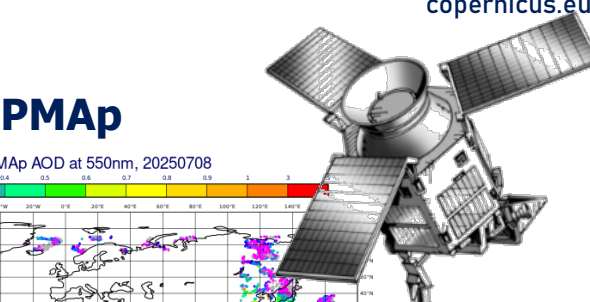
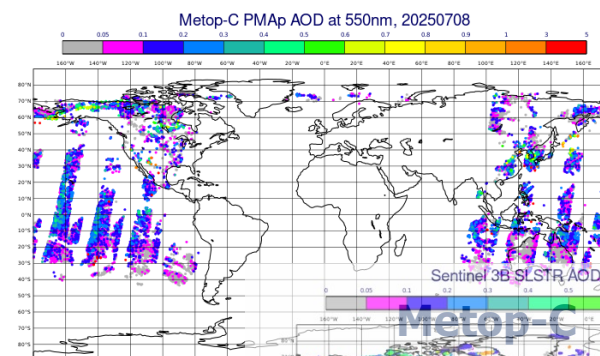
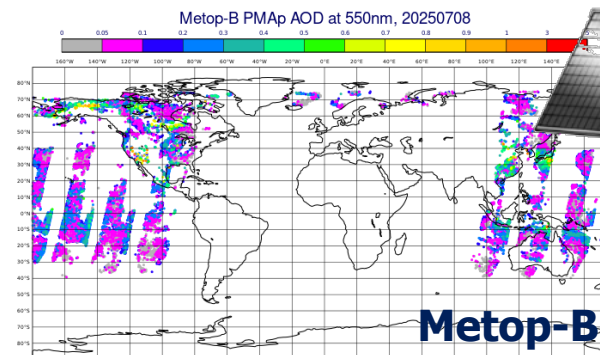
MODIS



VIIRS



PMAp



copernicus.eumetsat.int

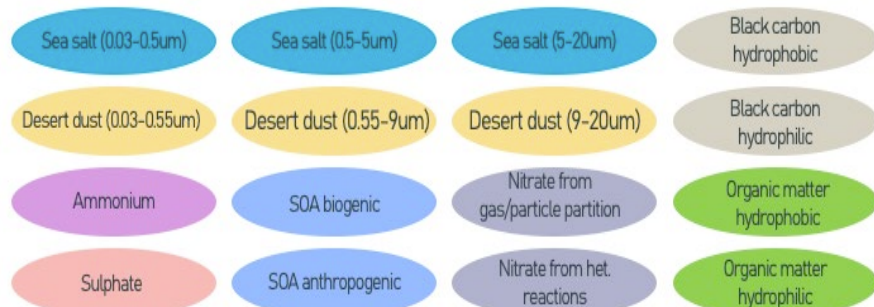
The satellite observations are:

- AOD retrievals at 550nm
- Total atmospheric column, total aerosol
- Visible daytime only

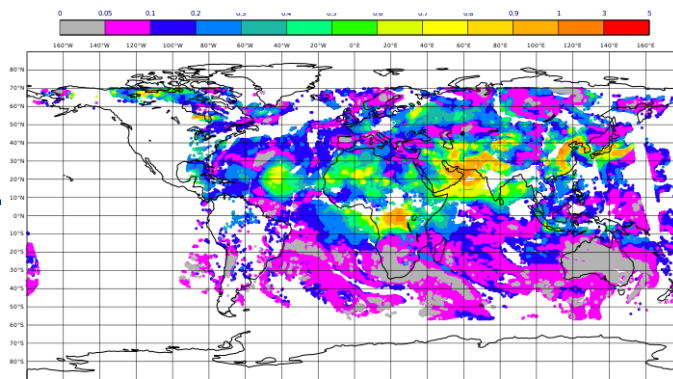
$$H_i[x_i]:$$

AOD Observation operator (model equivalent to observations):

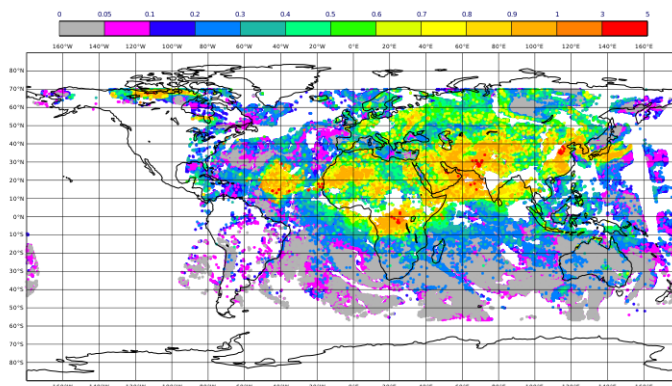
1. Interpolate aerosol mass mixing ratios from the individual aerosol tracers to obs location & time
2. Calculate model RH: it has an impact on hygroscopic aerosol
3. Get mass extinction coef at wavelength (e.g. 550nm) from a look-up table
4. Mutiply (3) * (1) to get single-species AODs
5. Total AOD is sum of single-species AOD



Model AOD



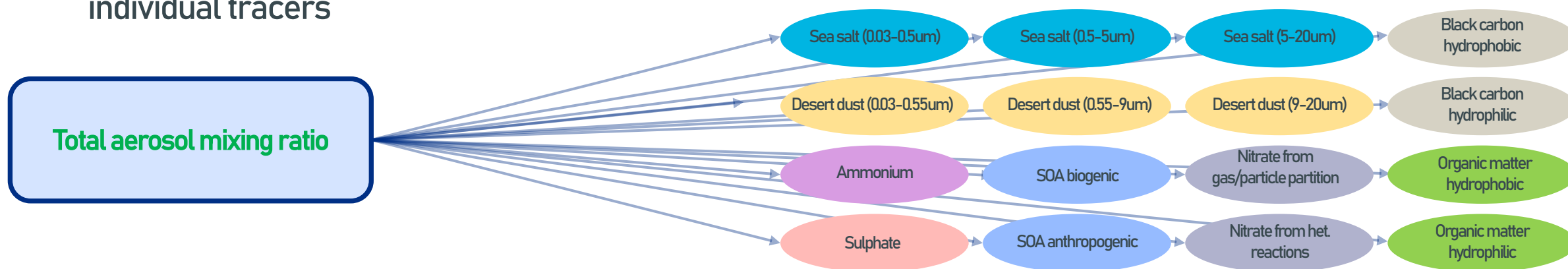
AOD Obs



Although we calculate AOD using all the aerosol tracers, there is not enough information it constrain them all and so we use “total aerosol” as the control variable

For aerosols we are trying to minimise the difference between the modelled AOD and the AOD observations, whilst not moving too far from our background or first guess model state

Model information from the background forecast (x_b) is used to divide the total aerosol increment from the minimisation of the cost function back into the individual tracers



- Largest contribution from dominant aerosol species
- Can not 'create' a tracer if not present in the background forecast
- The repartitioning of the total aerosol mixing ratio increment into the different bins can lead to problems with the aerosol speciation



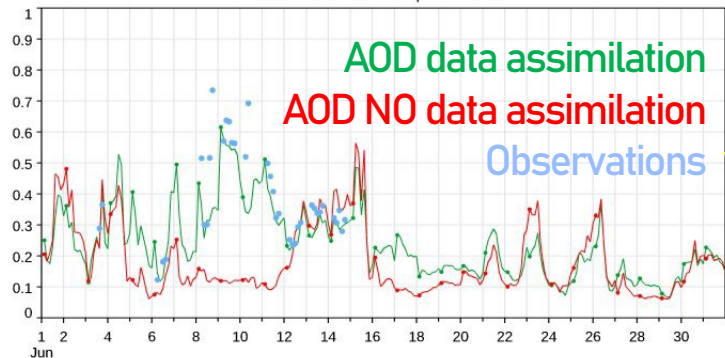
Why do data assimilation?

copernicus.eumetsat.int

Comparison of oper & icki and L1.5 Aeronet AOT at 500nm over
Payerne (46.81°N, 6.94°E).

1 Jun - 1 Jul 2025. 00Z, T+3 to 24. Ver0D 12.16.1.

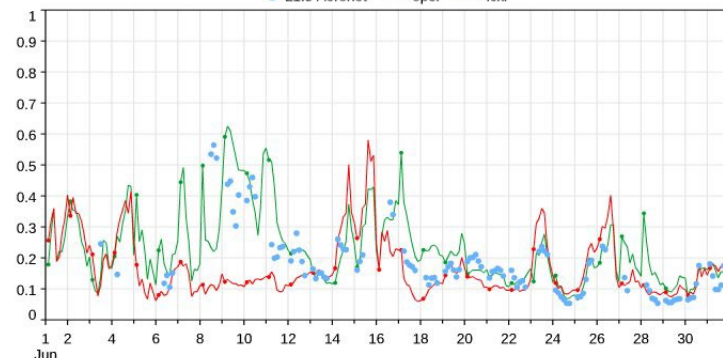
● L1.5 Aeronet — oper — icki



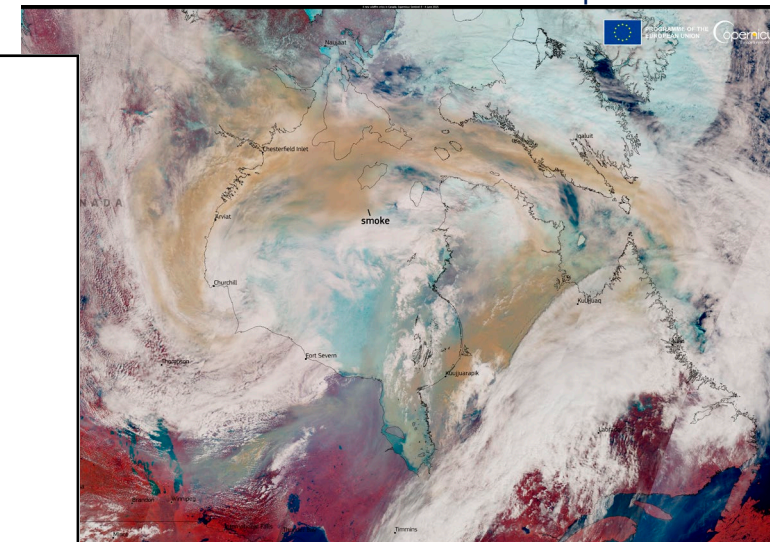
Comparison of oper & icki and L1.5 Aeronet AOT at 500nm over
HohenpeissenbergDWD (47.80°N, 11.01°E).

1 Jun - 1 Jul 2025. 00Z, T+3 to 24. Ver0D 12.16.1.

● L1.5 Aeronet — oper — icki



Aeronet verification: Comparison of the CAMS model, with and without data assimilation, against independent in-situ aeronet stations



Sentinel-3 satellited on 4 June (source: <https://www.copernicus.eu/en/media/image-day-gallery/new-wildfire-crisis-canada>).

Updating the forecast using real-time observations improves the forecast, particularly when there are significant aerosol events that the model does not capture.



Data Assimilation

What is it and how does it work for aerosols?

Challenges of DA for aerosols

Correcting different species height profiles of aerosols

Emission inversions for aerosols

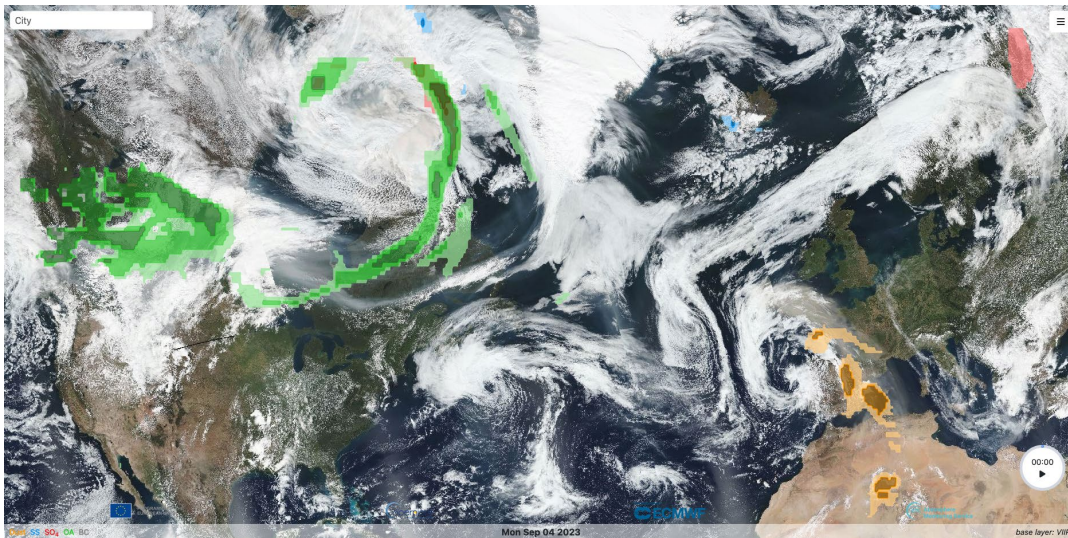
Can we use satellite aerosol observations to correct emissions?

CAMS aerosol applications

How are the aerosol forecasts used?

Dividing the total aerosol mixing ratio back into the individual aerosol tracers using forecast information can lead to issues with the speciation:

Good example

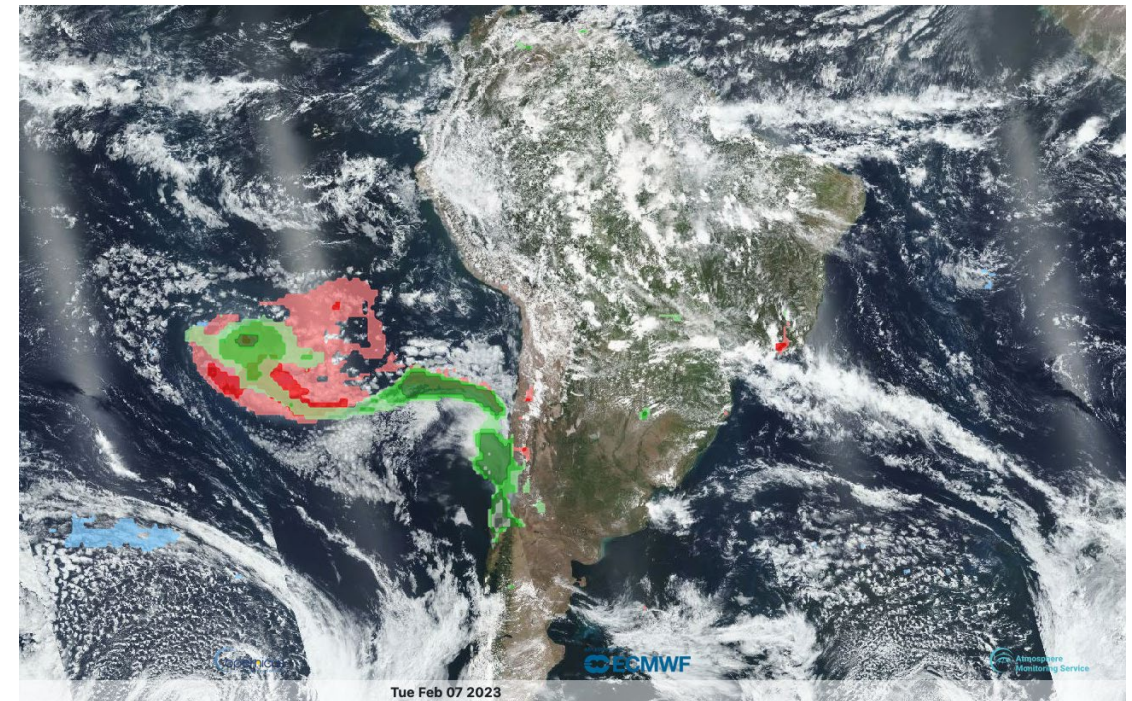


Organic matter, desert dust, sea salt, sulphate

CAMS aerosol alerts:

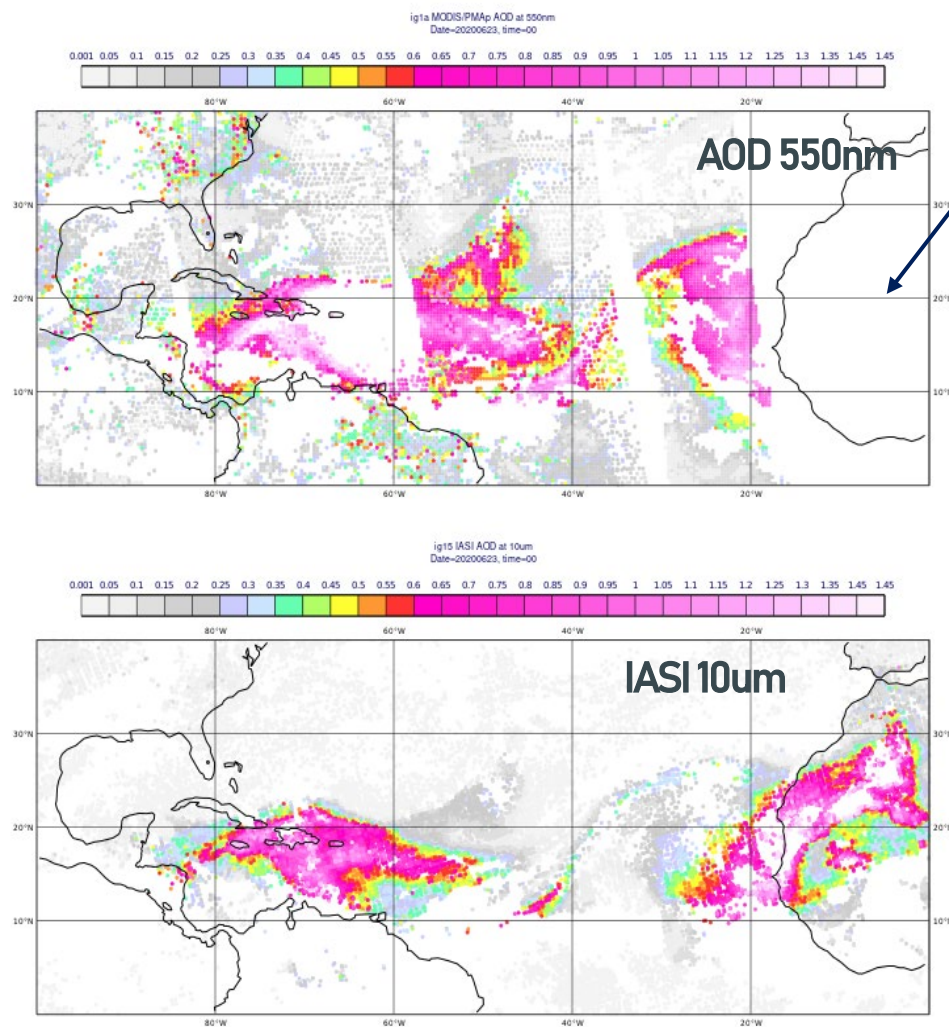
<https://aerosol-alerts.atmosphere.Copernicus.eu/>

Bad example



Part of fire plume is attributed to sulphate which is the dominant species in the background forecast

- Godzilla event in June 2020 – large incursion of Saharan dust across the Atlantic to the Caribbean



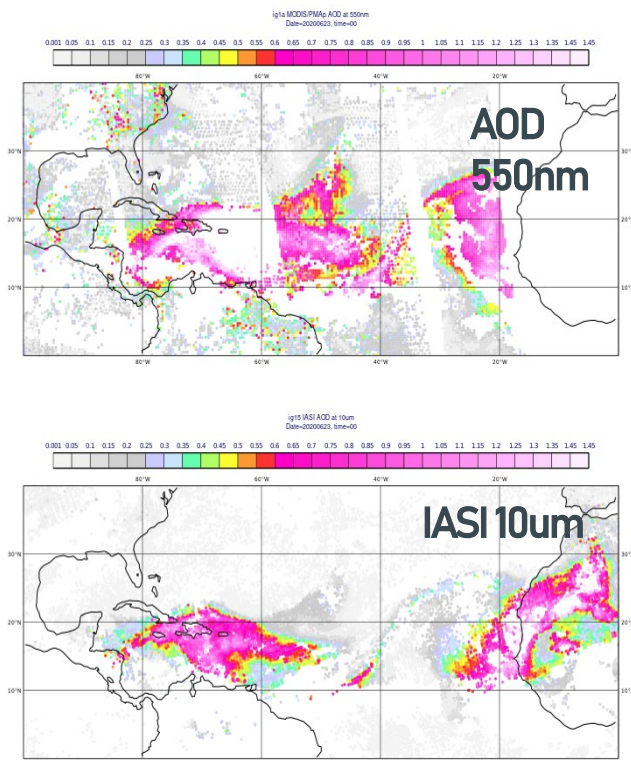
No night-time observations

- CAMS uses AOD 550nm obs from PMAp, MODIS and VIIRS with overpass times at 0930, 1030 and 1330
 - AOD at 550nm is in the visible spectrum and so is only measured in daylight hours
 - Total aerosol, total column measurement
-
- IASI 10um measures in the infrared spectrum and so is available in both day- and night-time
 - Onboard the Metop-B/C satellites with overpass times at 0930 (desc) and 2130 (asc)
 - Only measures coarse particles



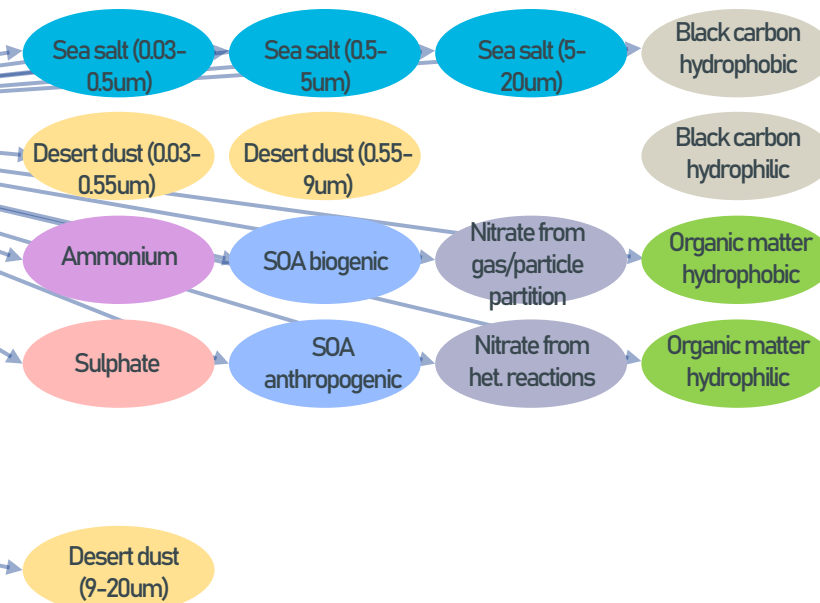
Coarse dust control variable

copernicus.eumetsat.int



Total aerosol mixing ratio

Coarse dust mixing ratio

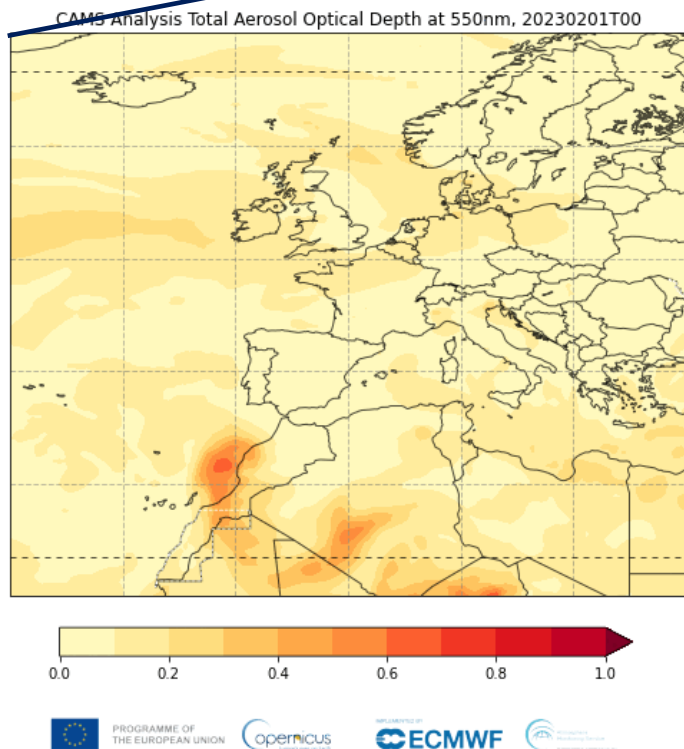




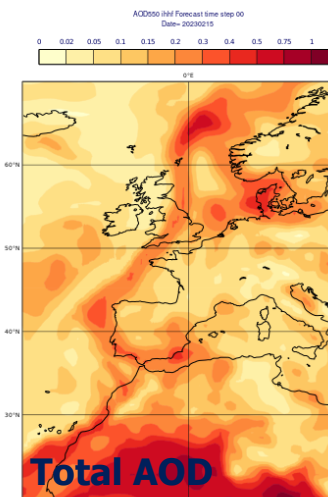
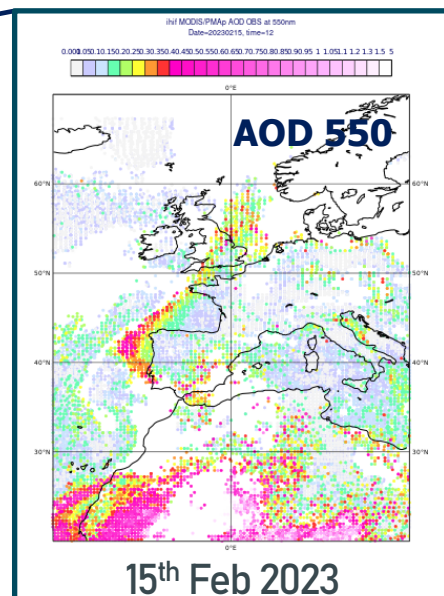
Can using IASI retrievals improve dust forecasts?

copernicus.eumetsat.int

Saharan dust plume over Europe in Feb 2023

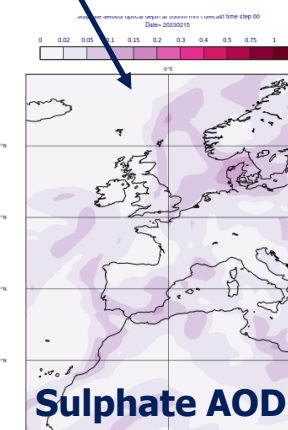
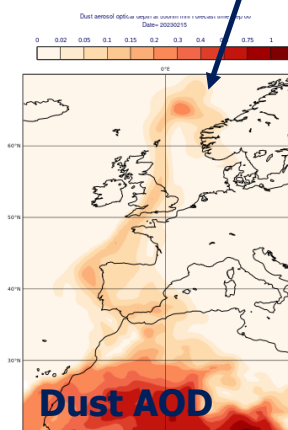


The model has an AOD plume that is very similar to the satellite observations



The total aerosol AOD increment calculated by the minimisation

The dust AOD increment based on the proportion of dust in the background forecast



The sulphate AOD increment based on the proportion of dust in the background forecast

Again, the division of the total increment into the individual tracers means the sulphate is increased, despite the fact that we know it is a plume of desert dust

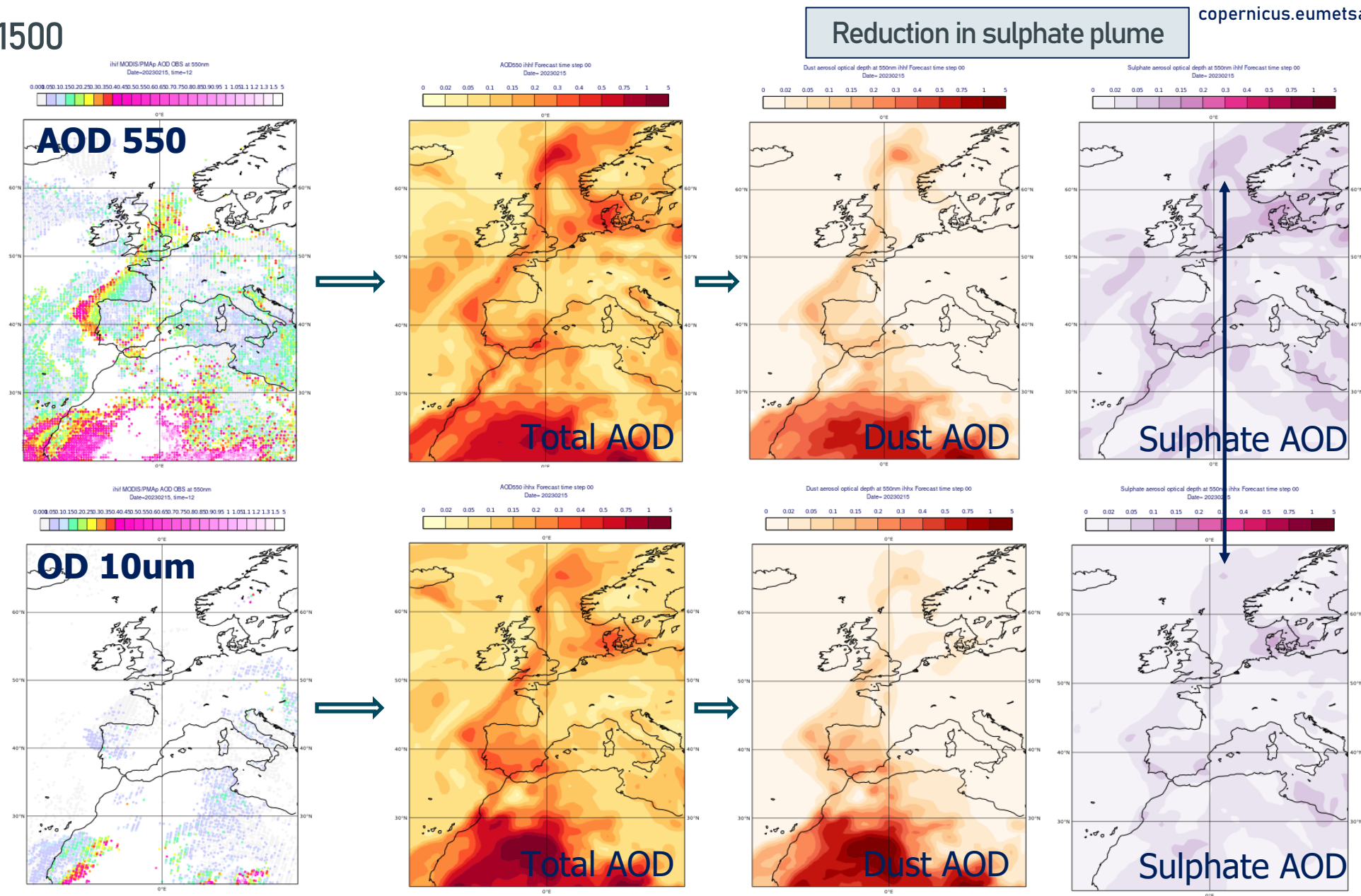


Can using IASI retrievals improve the dust forecast?

15th Feb 2023: 0300-1500

copernicus.eumetsat.int

- Using IASI OD 10 μ m observations reduces the sulphate plume
- Dust plume still present



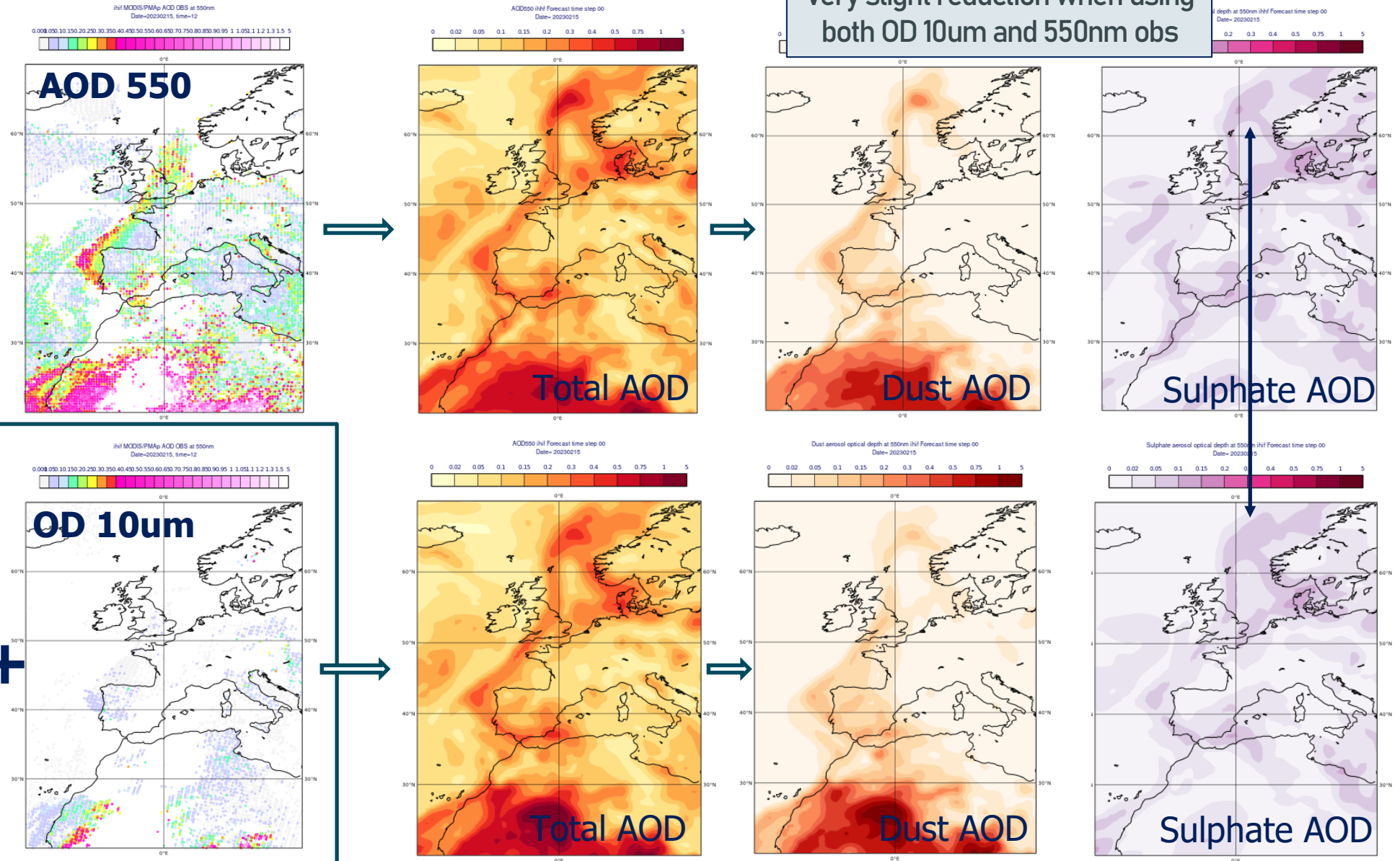


Can using IASI retrievals improve the dust forecast?

15th Feb 2023: 0300-1500

copernicus.eumetsat.int

- Using IASI OD 10 μ m observations reduces the sulphate plume
- Dust plume still present

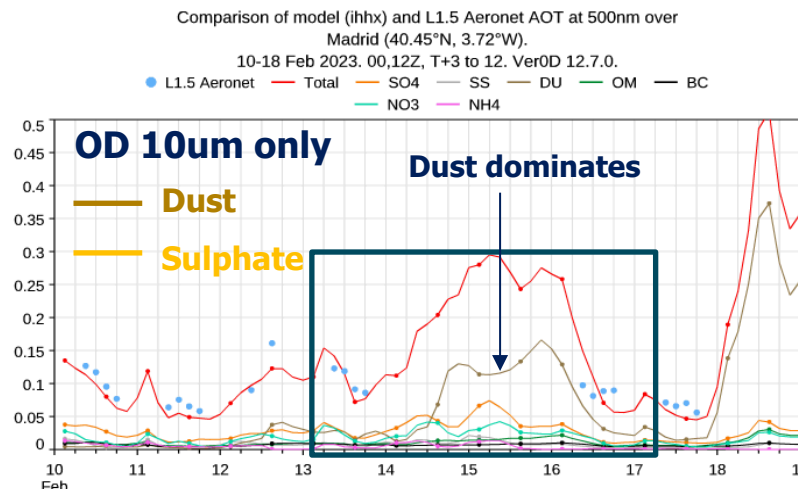
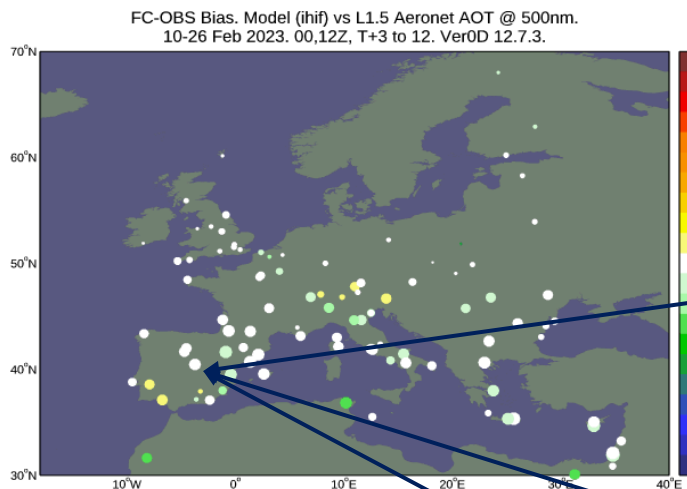




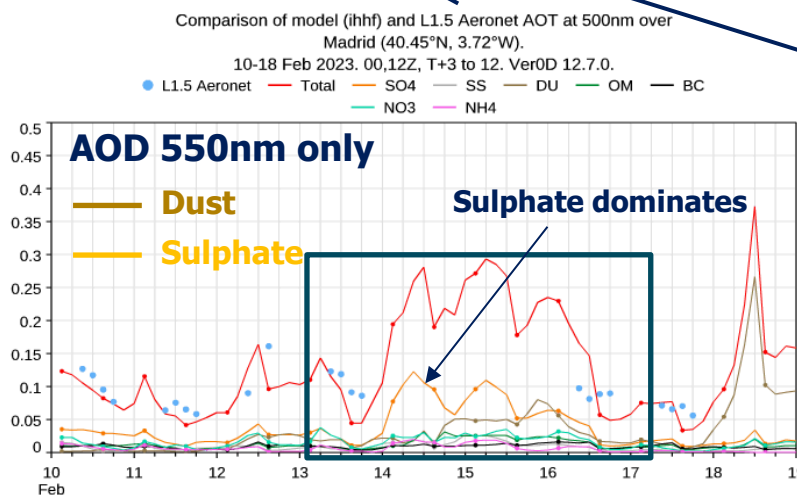
Can using IASI retrievals improve dust forecasts?

copernicus.eumetsat.int

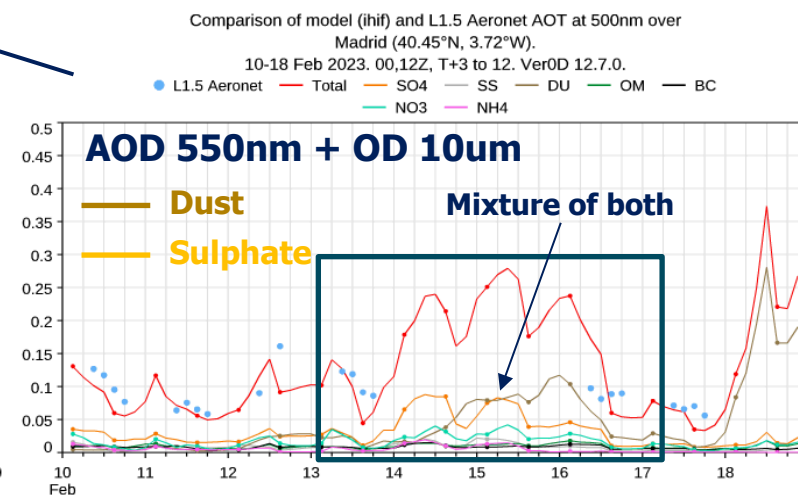
Saharan dust plume over Europe in Feb 2023



Only using IASI
10um obs leads to
dust being the
dominant species



Only using AOD
550nm obs leads to
sulphate being the
dominant species



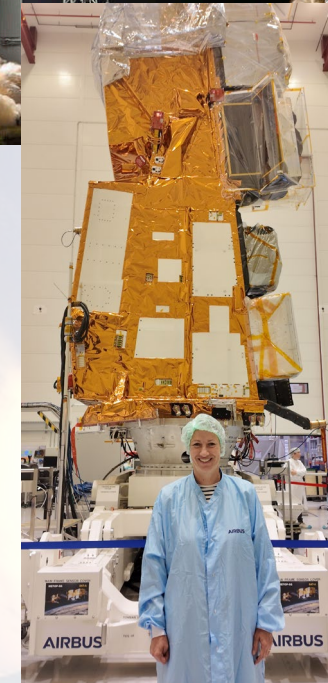
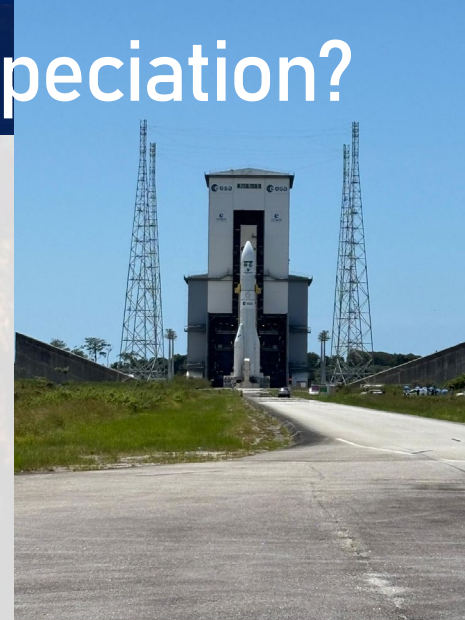
Using both types of
observations
means sulphate is
still present, but
dust gets more
weight

Aeronet verification at the Madrid station: different colours represent the different aerosol species



Can using 3MI retrievals improve speciation?

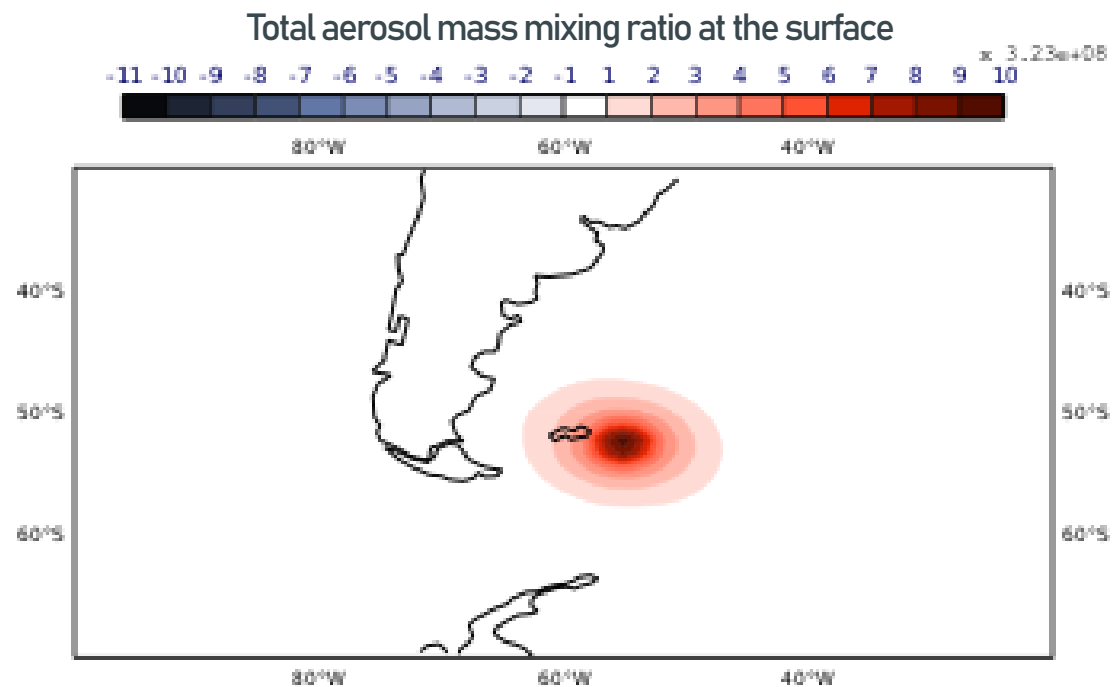
- Launched onboard MetOp-SG-A1 on the 13th August 2025
- 3MI – Multi-viewing Multi-channel Multi-polarisation Imager
 - The multiple viewing angles, wavelengths, polarisation channels enable additional information to be extracted about aerosols



AOD:	Aerosol Optical Depth	Standard total aerosol, total column observation
Fine and Coarse AOD:	Separates the AOD caused by fine and coarse particles	Enables aerosol species such as sulphate/fine dust to be constrained separately to coarse dust/sea-salt
AAOD:	Absorbing AOD	Applies to absorbing aerosol species, such as black carbon, dust and part of organic matter
SSA:	Single Scattering Albedo	Identifies aerosols that are more scattering, such as sulphate, nitrate and sea-salt
AE:	Angstrom Exponent	Distinguishes different sizes of aerosols

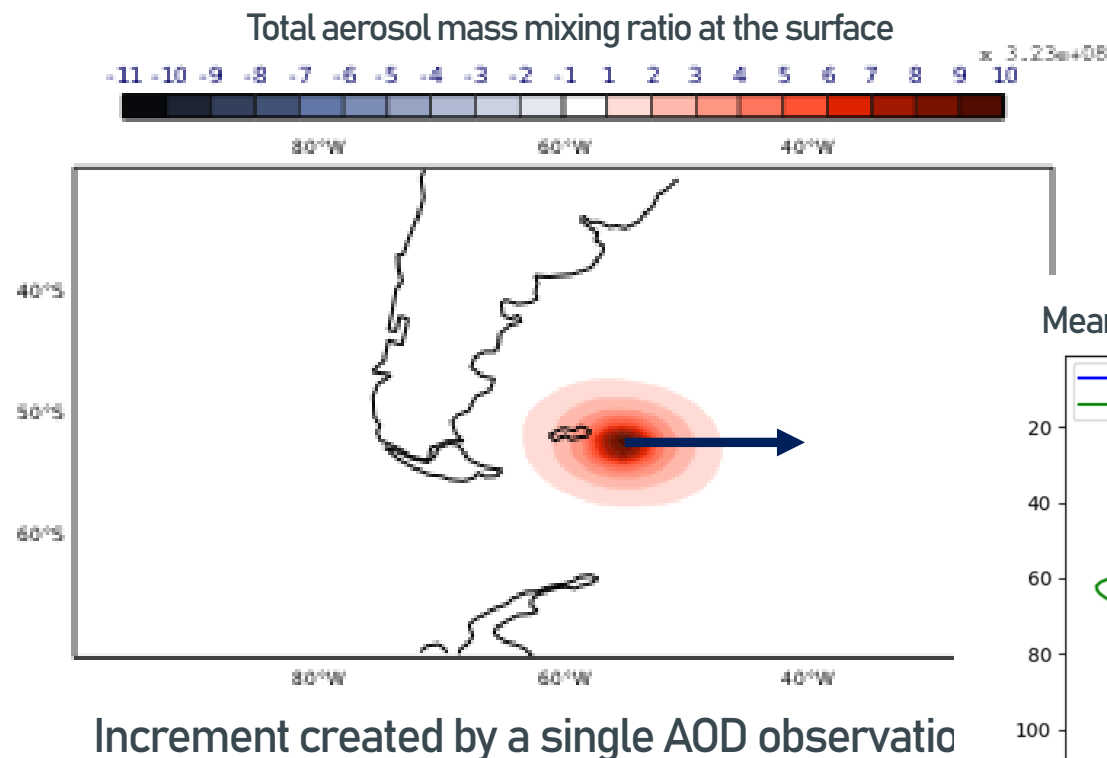
- How to use these new observations most effectively within the CAMS data assimilation set-up is an interesting current research question

See Rasmus
Lindstrot lecture

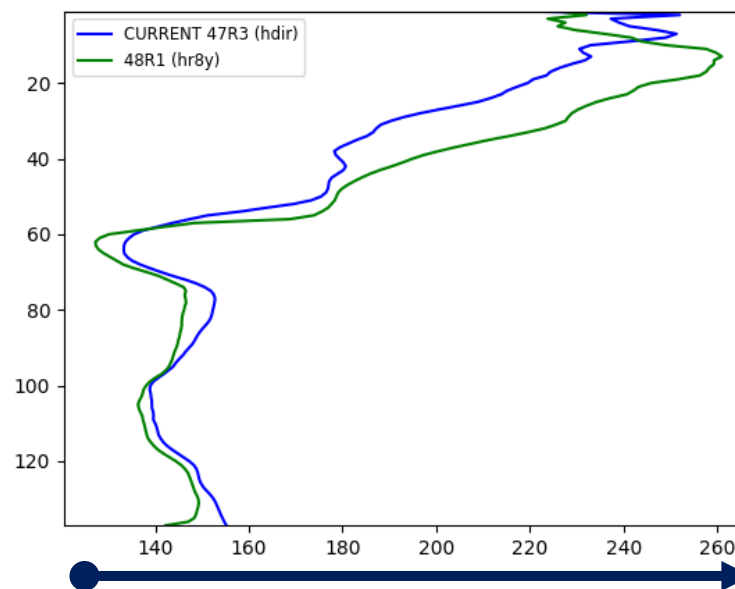


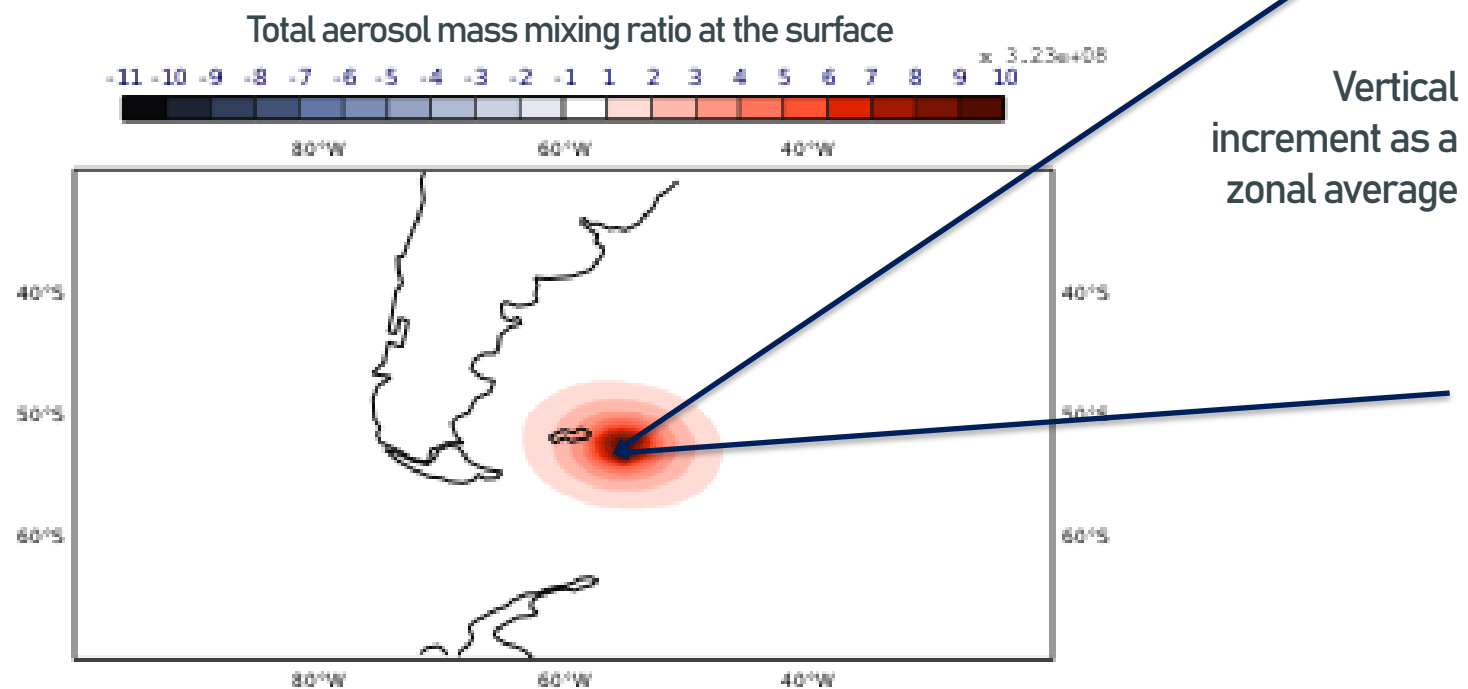
Increment created by a single AOD observation

- We calculate the background or model errors using the statistics from forecasts.
- The aim is to capture the uncertainty we have in our model
- We need to update this when we change our model

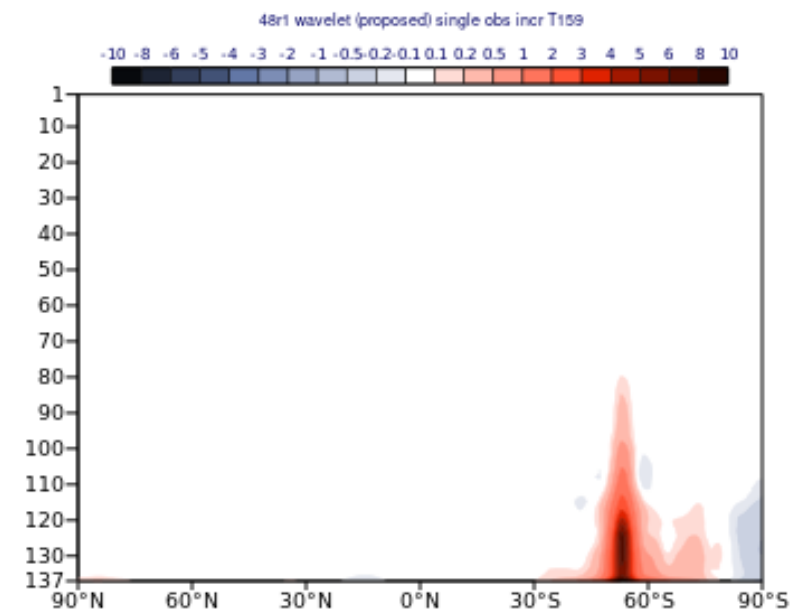


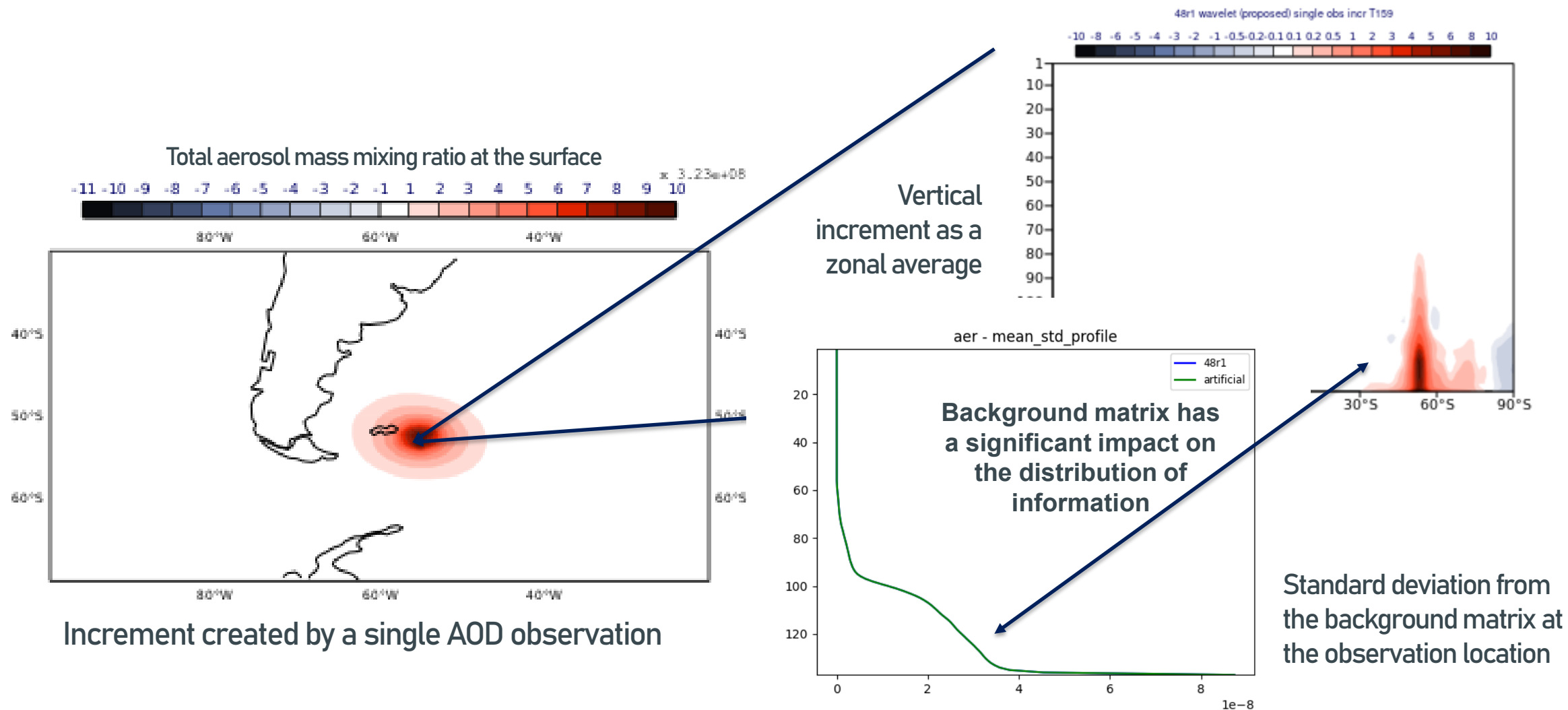
Mean lengthscale of horizontal aerosol correlations





Increment created by a single AOD observation



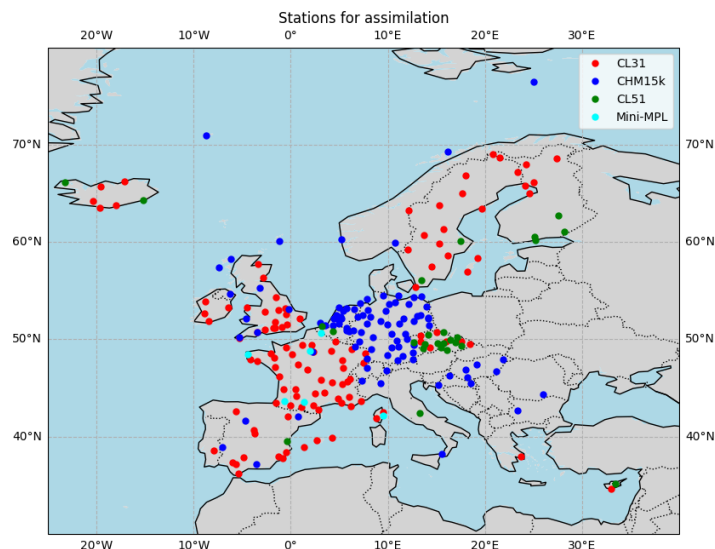


With no profile observations, formulation of the B-matrix is very important for how the AOD information is distributed in the vertical



Available operational profile observations

copernicus.eumetsat.int

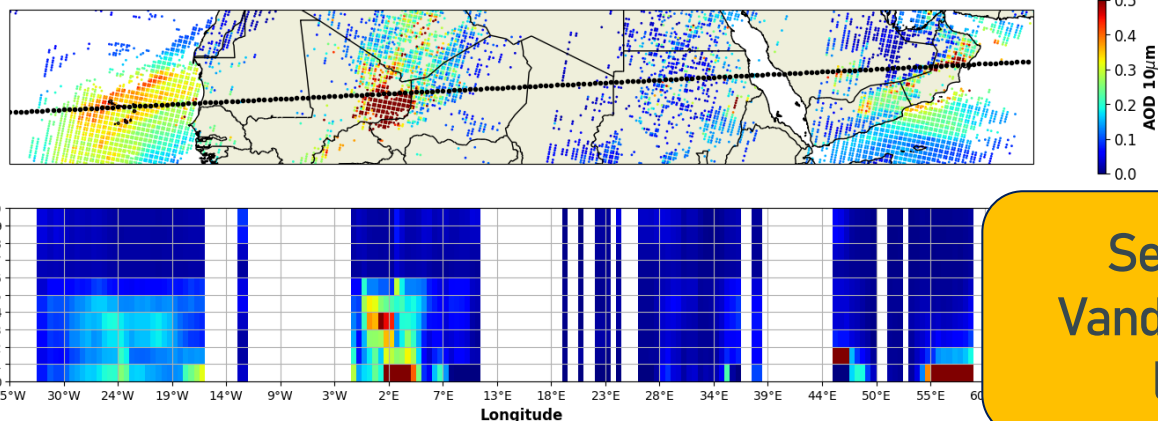


E-PROFILE network

- Network of lidar and ceilometer instruments based across Europe
- Profile observations of aerosol attenuated backscatter
- Regional and in-situ observations
- Operationally disseminated

MAPIR IASI 10um dust profiles

- Covered by Sophie's lecture yesterday
- In the process of becoming operationally available
- Coarse profiles but of a specific aerosol species

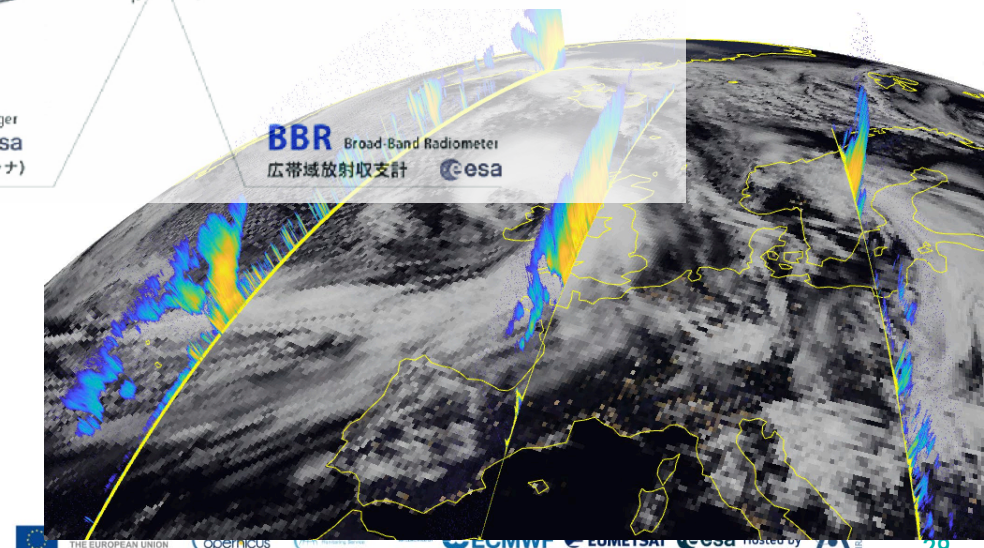
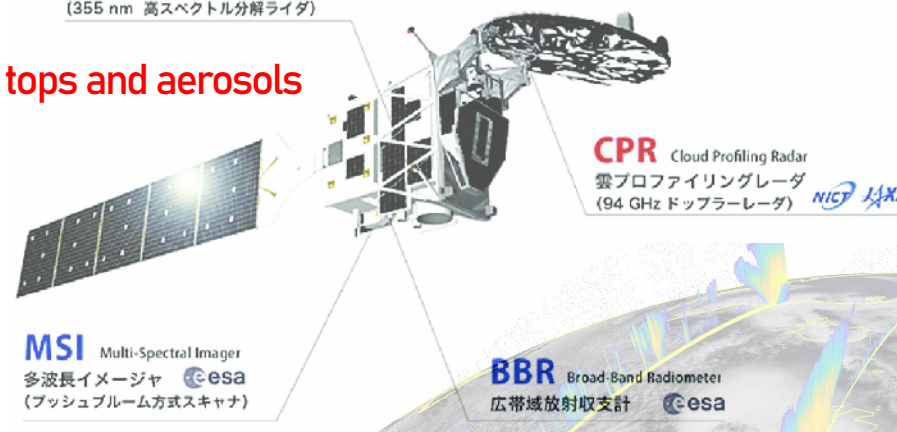


See Sophie
Vandenbussche
lecture

EarthCARE

- Satellite observations that provide a profile of aerosol
- Global coverage
- In the process of becoming operationally available

ATLID Atmospheric Lidar
大気ライダ (355 nm 高スペクトル分解ライダ)



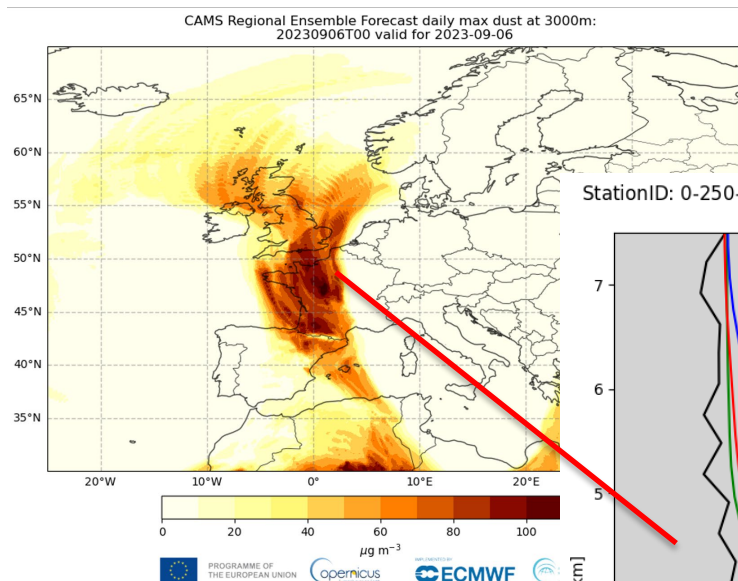


Assimilating E-Profile data

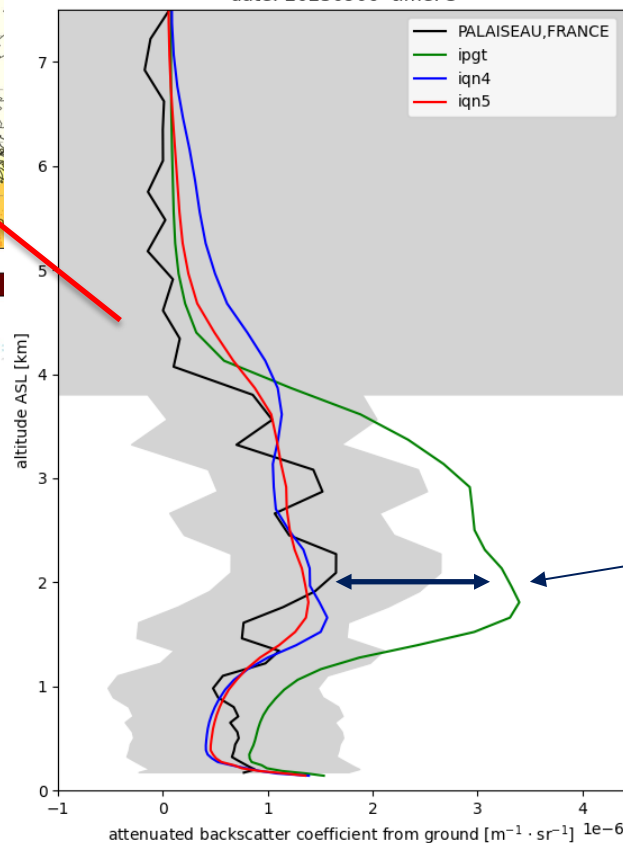
copernicus.eumetsat.int

Saharan dust storm Sept 2023

Canadian wildfires August 2024



StationID: 0-250-1001-07151 Instrument: CHM15k $\lambda = 1064.0$ nm
date: 20230906 time: 3



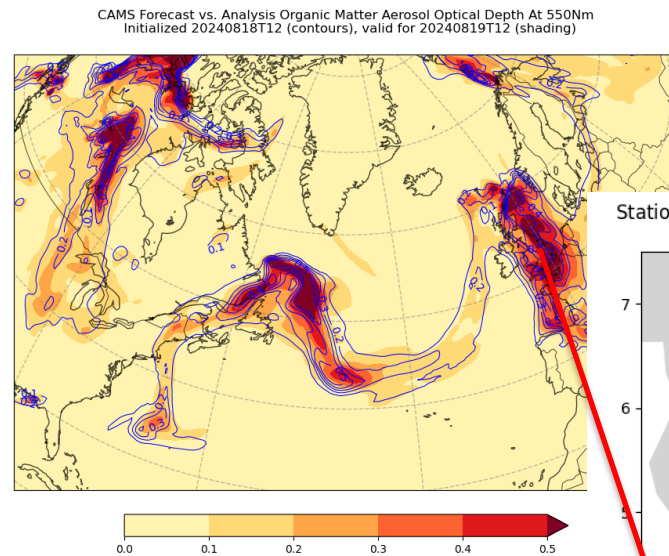
Obs

Ctrl (AOD assimilation only)

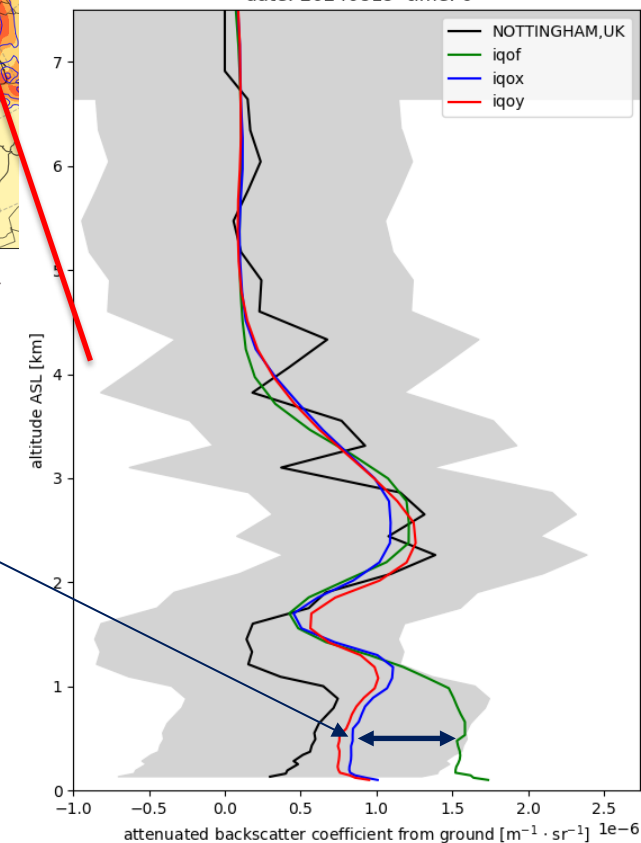
E-PROFILE (spheres)

E-PROFILE (spheroids)

Non-assimilated E-PROFILE station



StationID: 0-20000-0-03354 Instrument: CHM15k $\lambda = 1064.0$ nm
date: 20240819 time: 0



Assimilating profile
observations on top of AOD
improves the profile of total
aerosol from the model

Non-assimilated E-PROFILE station



Assimilating MAPIR IASI profile data

copernicus.eumetsat.int

IASI MAPIR profile retrievals use the same methodology as data assimilation – minimize a cost function that contains the observations and some a-priori constraint

$$\hat{y} = y_a + \mathbf{A}(y - y_a) + \varepsilon$$

Retrieved value: true state y smoothed by the averaging kernel \mathbf{A} ;
 y_a : a-priori, ε : retrieval error

See Sophie
Vandenbussche
lecture

See Antje Inness's talk from last year's training for further details



Assimilating MAPIR IASI profile data

copernicus.eumetsat.int

IASI MAPIR profile retrievals use the same methodology as data assimilation – minimize a cost function that contains the observations and some a-priori constraint

$$\hat{y} = y_a + \mathbf{A}(y - y_a) + \varepsilon$$

Retrieved value: true state y smoothed by the averaging kernel \mathbf{A} ;
 y_a : a-priori, ε : retrieval error

See Sophie
Vandenbussche
lecture

$$d = \hat{y} - H(\mathbf{x}_m) = y_a + \mathbf{A}(y - y_a) + \varepsilon - H(\mathbf{x}_m)$$

Without averaging kernels in observation operator
(e.g. simple vertical integral)

Option 1:

- Transform the model to match the observation units
- Interpolate to the time and location/height of the profile

See Antje Inness's talk from last year's training for further details



Assimilating MAPIR IASI profile data

copernicus.eumetsat.int

IASI MAPIR profile retrievals use the same methodology as data assimilation – minimize a cost function that contains the observations and some a-priori constraint

$$\hat{y} = y_a + A(y - y_a) + \varepsilon$$

Retrieved value: true state y smoothed by the averaging kernel A ;
 y_a : a-priori, ε : retrieval error

See Sophie
Vandenbussche
lecture

$$d = \hat{y} - H(\mathbf{x}_m) = y_a + A(y - y_a) + \varepsilon - H(\mathbf{x}_m)$$

Without averaging kernels in observation operator
(e.g. simple vertical integral)

Prior information has an impact
on the difference between the
retrieval and the model

Option 1:

- Transform the model to match the observation units
- Interpolate to the time and location/height of the profile

See Antje Inness's talk from last year's training for further details

IASI MAPIR profile retrievals use the same methodology as data assimilation – minimize a cost function that contains the observations and some a-priori constraint

$$\hat{y} = y_a + \mathbf{A}(y - y_a) + \varepsilon$$

Retrieved value: true state y smoothed by the averaging kernel \mathbf{A} ;
 y_a : a-priori, ε : retrieval error

See Sophie
Vandenbussche
lecture

$$d = \hat{y} - H(\mathbf{x}_m) = y_a + \mathbf{A}(y - y_a) + \varepsilon - H(\mathbf{x}_m)$$

Without averaging kernels in observation operator
 (e.g. simple vertical integral)

$$\begin{aligned} d &= \hat{y} - \hat{H}(\mathbf{x}_m) = y_a + \mathbf{A}(y - y_a) + \varepsilon - (y_a + \mathbf{A}(H(\mathbf{x}_m) - y_a)) \\ &= \mathbf{A}(y - H(\mathbf{x}_m)) + \varepsilon \end{aligned}$$

With averaging kernels in
observation operator

Option 2:

- Transform the model to match the observation units
- Interpolate to the time and location/height of the profile
- Remove the prior profile
- Apply the averaging kernel
- Add the prior profile



Assimilating MAPIR IASI profile data

copernicus.eumetsat.int

IASI MAPIR profile retrievals use the same methodology as data assimilation – minimize a cost function that contains the observations and some a-priori constraint

$$\hat{y} = y_a + \mathbf{A}(y - y_a) + \varepsilon$$

Retrieved value: true state y smoothed by the averaging kernel \mathbf{A} ;
 y_a : a-priori, ε : retrieval error

See Sophie
Vandenbussche
lecture

$$d = \hat{y} - H(\mathbf{x}_m) = y_a + \mathbf{A}(y - y_a) + \varepsilon - H(\mathbf{x}_m)$$

Without averaging kernels in observation operator
(e.g. simple vertical integral)

$$d = \hat{y} - \hat{H}(\mathbf{x}_m) = y_a + \mathbf{A}(y - y_a) + \varepsilon - (y_a + \mathbf{A}(H(\mathbf{x}_m) - y_a))$$

$$= \mathbf{A}(y - H(\mathbf{x}_m)) + \varepsilon$$

With averaging kernels in
observation operator

No longer any impact of the
prior and the comparison now
becomes between the model
value and the “truth”

Option 2:

- Transform the model to match the observation units
- Interpolate to the time and location/height of the profile
- Remove the prior profile
- Apply the averaging kernel
- Add the prior profile

IASI MAPIR profile retrievals use the same methodology as data assimilation – minimize a cost function that contains the observations and some a-priori constraint

$$\hat{y} = y_a + \mathbf{A}(y - y_a) + \varepsilon$$

Retrieved value: true state y smoothed by the averaging kernel \mathbf{A} ;
 y_a : a-priori, ε : retrieval error

See Sophie
Vandenbussche
lecture

$$d = \hat{y} - H(\mathbf{x}_m) = y_a + \mathbf{A}(y - y_a) + \varepsilon - H(\mathbf{x}_m)$$

Without averaging kernels in observation operator
(e.g. simple vertical integral)

$$\begin{aligned} d &= \hat{y} - \hat{H}(\mathbf{x}_m) = y_a + \mathbf{A}(y - y_a) + \varepsilon - (y_a + \mathbf{A}(H(\mathbf{x}_m) - y_a)) \\ &= \mathbf{A}(y - H(\mathbf{x}_m)) + \varepsilon \end{aligned}$$

With averaging kernels in
observation operator

- We remove the influence of the a-priori profile if we use the averaging kernel to sample the model profile according to the assumptions made in the retrieval
- The model data is smoothed by the averaging kernel to produce a profile or column that is directly comparable to the product derived from the instrument radiances
- We still need to know y_a and \mathbf{A} in the observation operator calculations



Data Assimilation

What is it and how does it work for aerosols?

Challenges of DA for aerosols

Correcting different species height profiles of aerosols

Emission inversions for aerosols

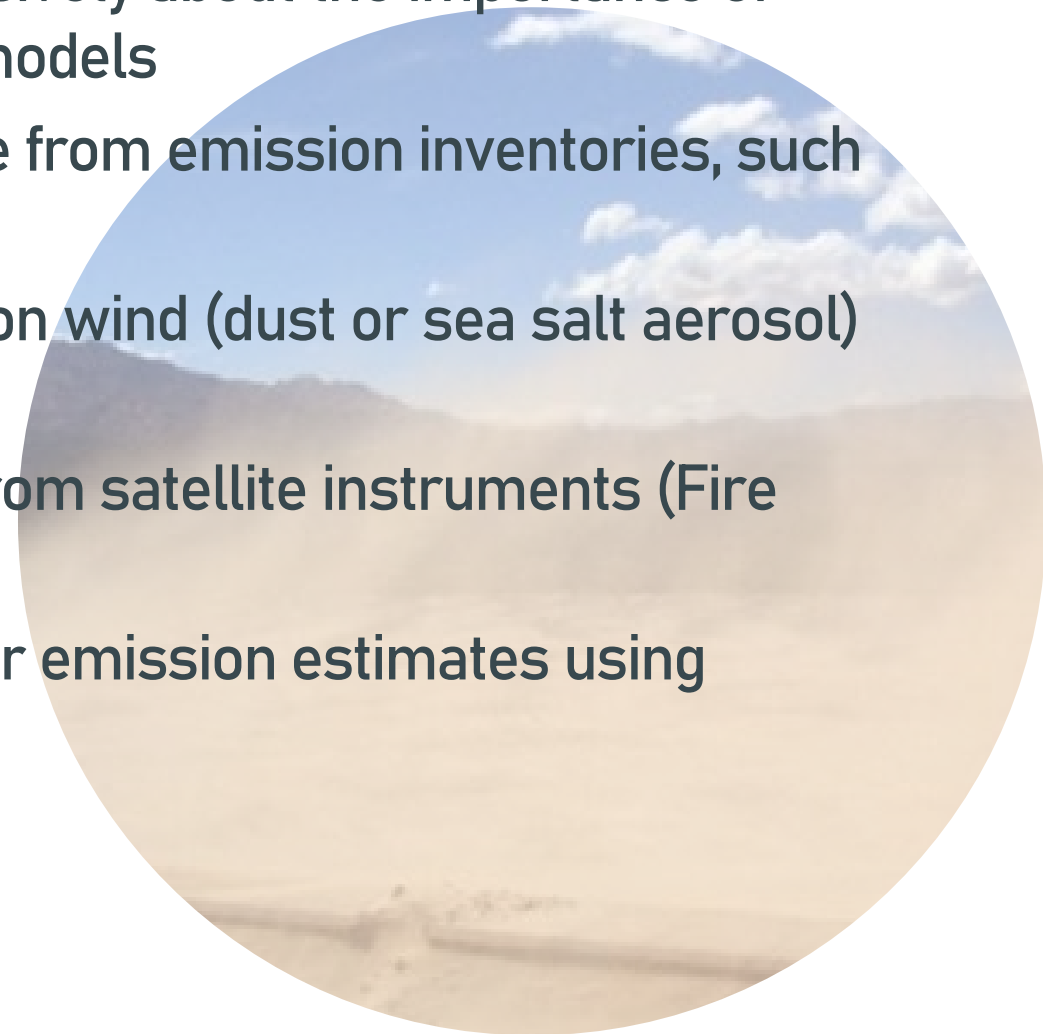
Can we use satellite aerosol observations to correct emissions?

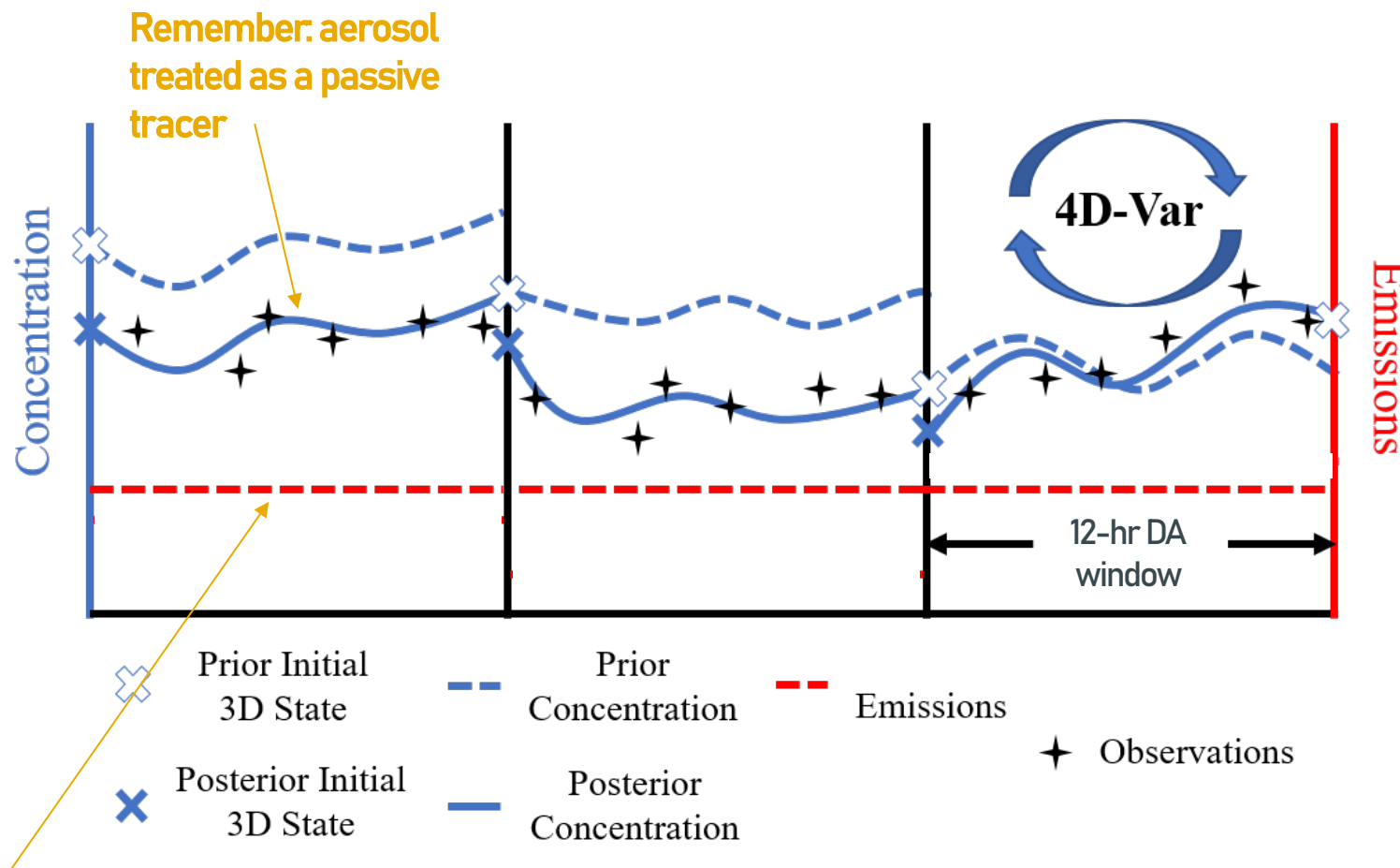
CAMS aerosol applications

How are the aerosol forecasts used?

- Samuel Remy has already talked comprehensively about the importance of emissions as an input parameter to aerosol models
- Some of the relevant aerosol emissions come from emission inventories, such as SO₂
- Other emissions are calculated online based on wind (dust or sea salt aerosol) or temperature (biogenic emissions)
- Some emissions can be observed indirectly from satellite instruments (Fire radiative power, burnt area, volcanic plumes)
- “Inverse” methods can be used to correct prior emission estimates using observations of concentrations and models

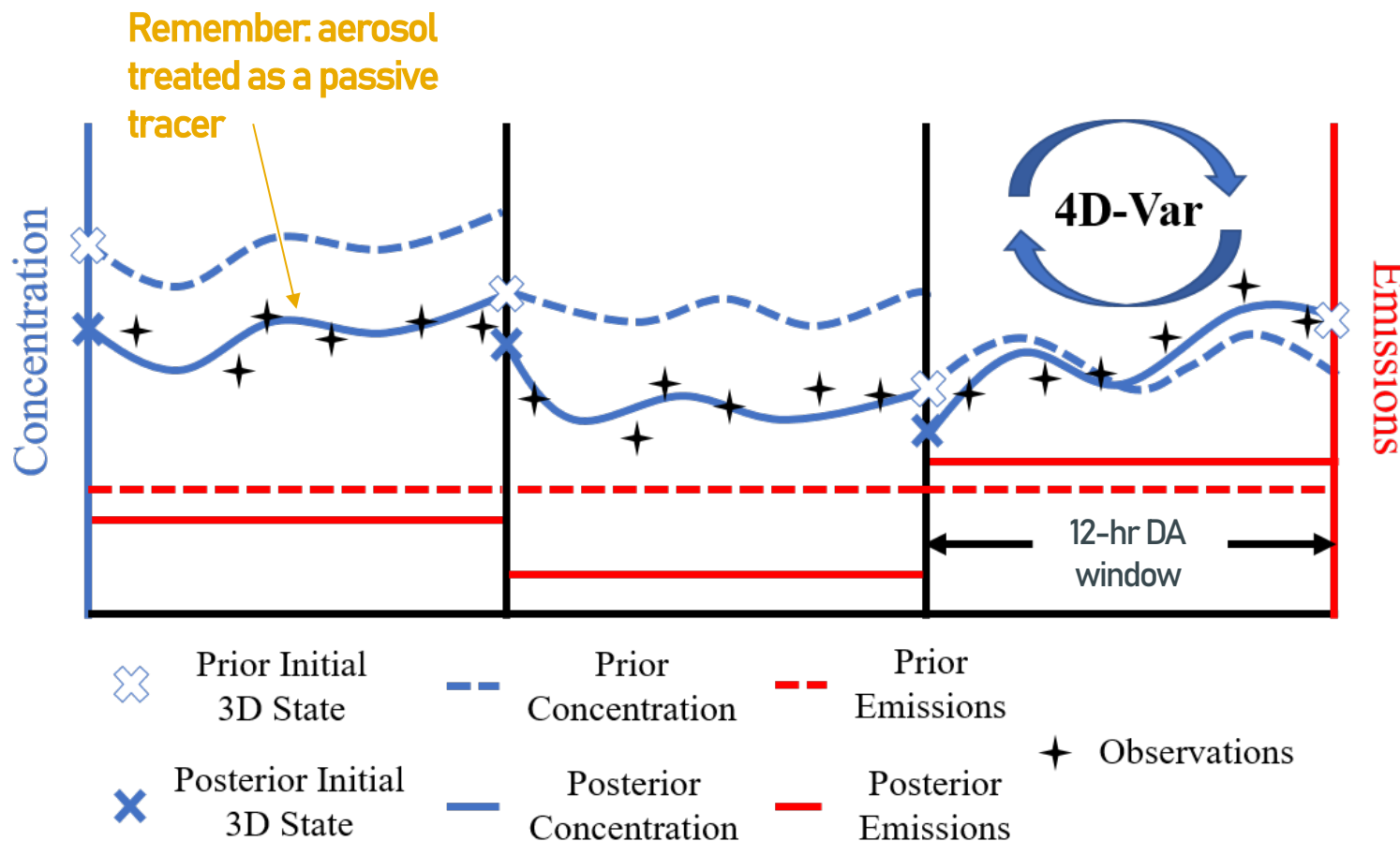
See Samuel
Remy lecture





NWP 4D-Var is mostly defined as an initial value problem. Only initial conditions are changed, and model error is relatively small

Emissions assumed constant over the 12hr window



NWP 4D-Var is mostly defined as an initial value problem. Only initial conditions are changed, and model error is relatively small

How to improve?

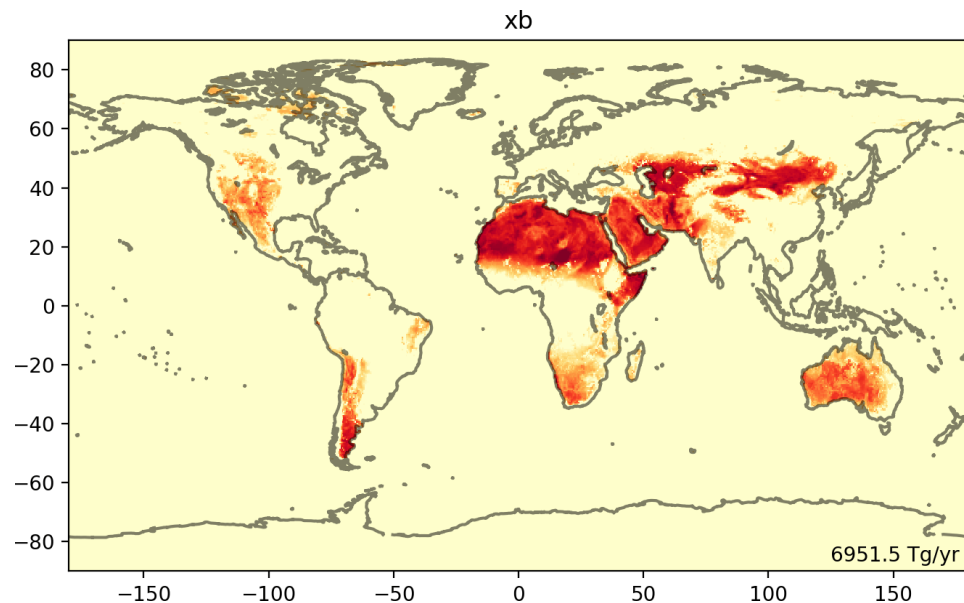
Use the data assimilation system to adjust surface fluxes at the same time as the initial conditions

$$J(x, p) = \underbrace{(x - x_b)^T B^{-1} (x - x_b)}_{J_b: \text{background constraint for } x} + \underbrace{(p - p_b)^T B_p^{-1} (p - p_b)}_{J_p: \text{constraint for emission scaling factors}} + \underbrace{\sum_{i=0}^n (y_i - H_i[x_i, p])^T R_i^{-1} (y_i - H_i[x_i, p])}_{J_o: \text{observation constraint}}$$

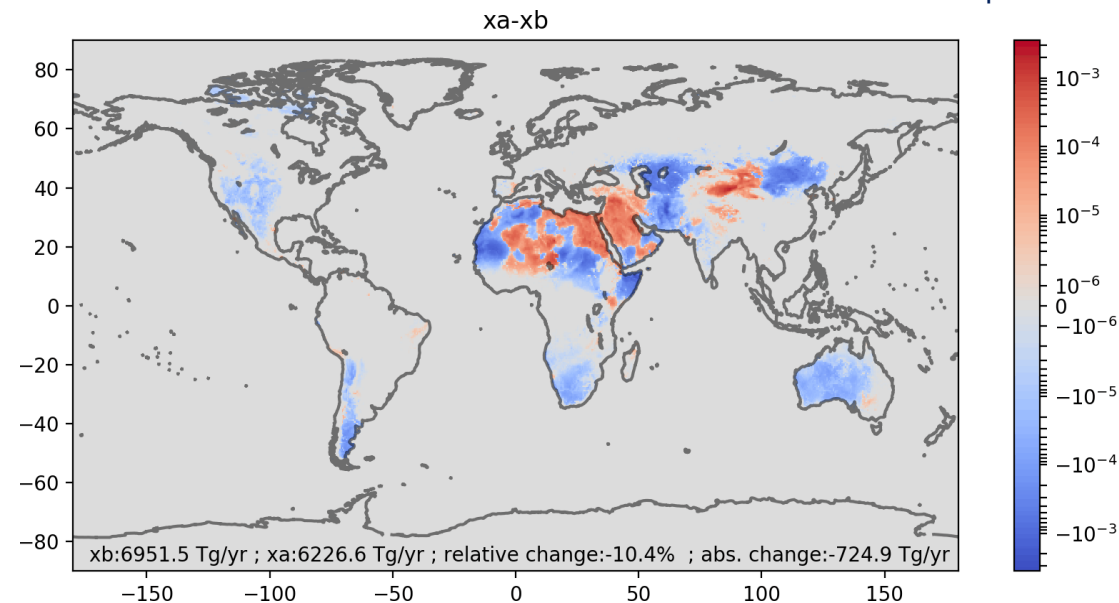
State control vector

Parameter (e.g. scaling factors)

- Joint optimisation of emissions and initial conditions
- Optimised emissions for dust
- TL/AD of simplified dust emissions; currently no dust emissions are included within the minimisation process
- 2D scaling factors p applied to emission fields
- Prior error definition:
 - Global constant or 2D map of standard error
 - Spatial correlation length scale (via B_p)



Yearly averaged dust emissions for 2017



Yearly averaged emission increments
for 2017 due to scaling factors

- Untangling the signal from total AOD into the emissions for a specific tracer would be very complicated, if not impossible
- More feasible is using specific aerosol species observations to constrain the emissions of that species
- VIIRS dust flagged AOD observations used to produce scaling factors for IFS dust emissions as part of the CAMAERA HE project
- IASI 10 μ m AOD would also be another option, since it targets coarse dust.

HE CAMAERA project results



Data Assimilation

What is it and how does it work for aerosols?

Challenges of DA for aerosols

Correcting different species height profiles of aerosols

Emission inversions for aerosols

Can we use satellite aerosol observations to correct emissions?

CAMS aerosol applications

How are the aerosol forecasts used?

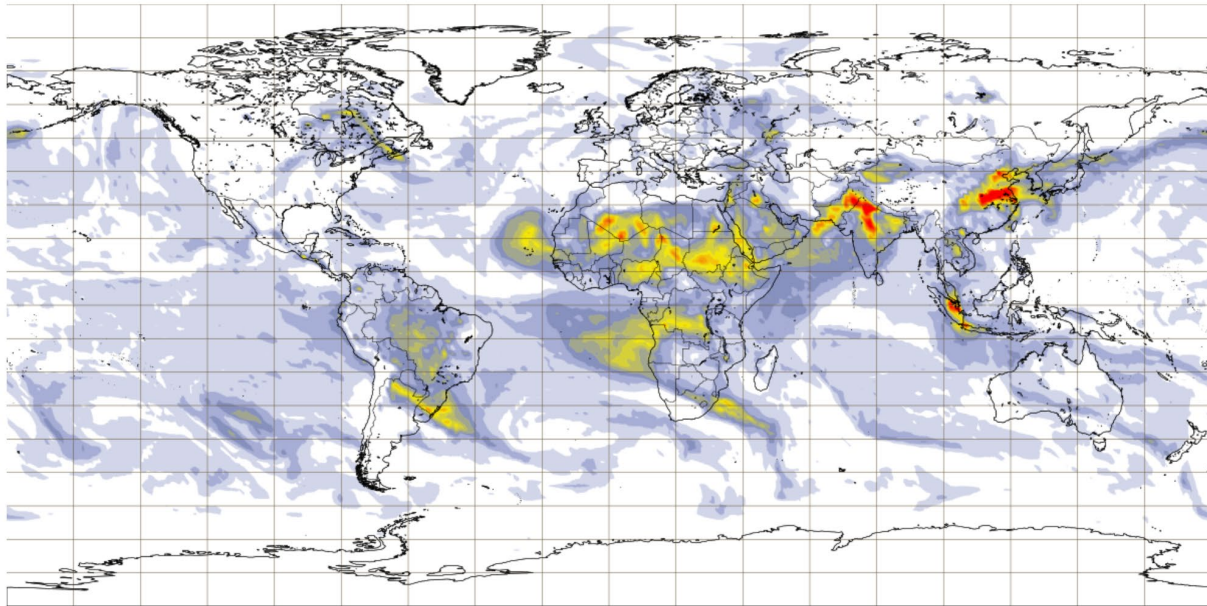
Forecasts (aerosol alert service)

copernicus.eumetsat.int

- CAMS produces two five-day forecasts every day
- These start from initial conditions at 0300 and 1500 calculated through data assimilation
- They are freely available from the CAMS website

Aerosol forecasts

Base time: Wed 01 Oct 2025 00 UTC Valid time: Mon 06 Oct 2025 00 UTC (+120h) Area : Global Aerosol type : Total aerosol

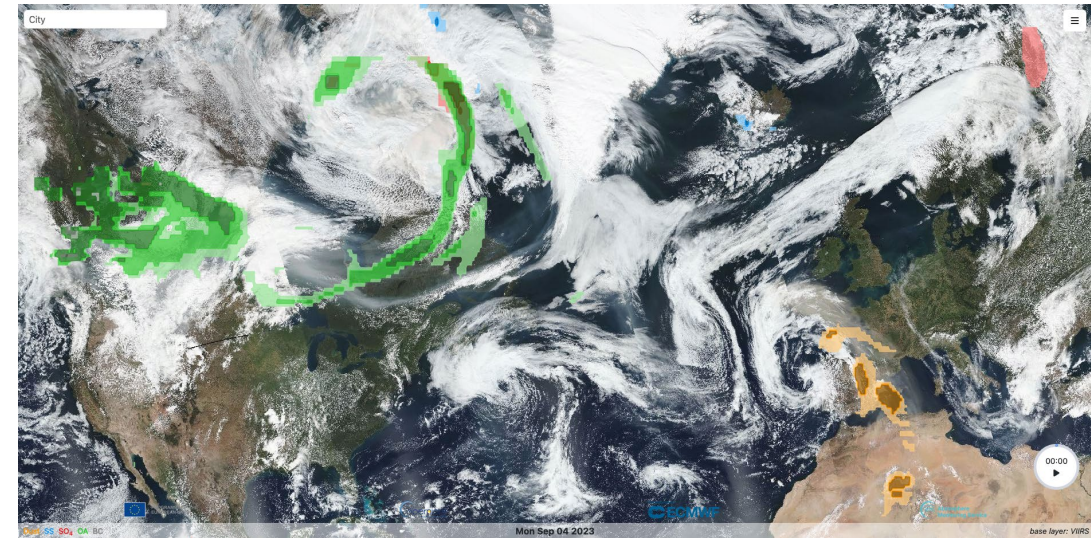


Aerosol optical depth at 550 nm (provided by CAMS, the Copernicus Atmosphere Monitoring Service) (default)

0.1 0.16 0.23 0.29 0.36 0.42 0.49 0.55 0.61 0.68 0.74 0.81 0.87 0.94 3

CAMS aerosol alerts:

<https://aerosol-alerts.atmosphere.Copernicus.eu/>



Organic matter, desert dust, sea salt, sulphate

- The CAMS aerosol alert service provides daily warnings for significant events like forest fires, dust storms, and intense anthropogenic pollution episodes
- Register to the service and get specific warnings tailored to your requirements

<https://atmosphere.copernicus.eu/charts/packages/cams/>

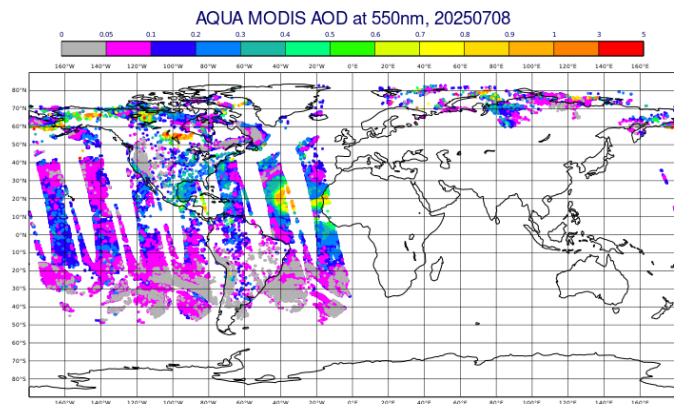
- CAMS provides policy tools to help identify the source, sector and quantity of PM
 - Chemical species of aerosol
 - Country impact/contribution
 - Sector apportionment
 - Policy scenarios

<https://atmosphere.copernicus.eu/policy-tools>



For more information and additional results (past results, comparisons with [observations](#), [source tagging](#), and [custom scenarios](#)), check out the other [daily source attribution](#) products.

- Air quality is a very important aspect of the work of CAMS
- Surface quantity, which is impacted by short- and long-range aerosols
- PM₁₀ – Particulate Matter smaller than 10µm

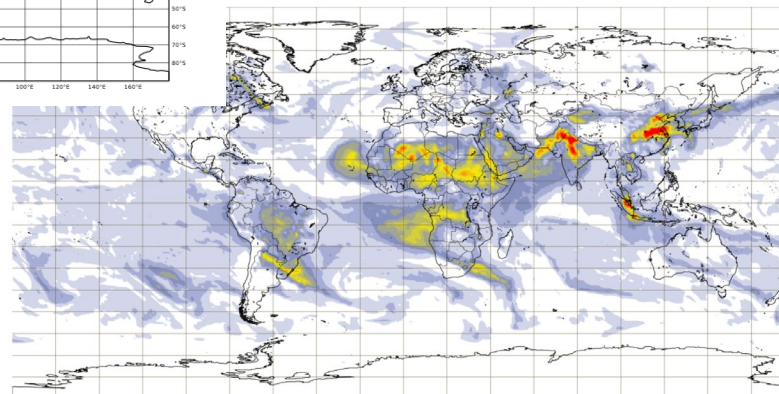


Using observations to
update forecasts keeps
models close to reality



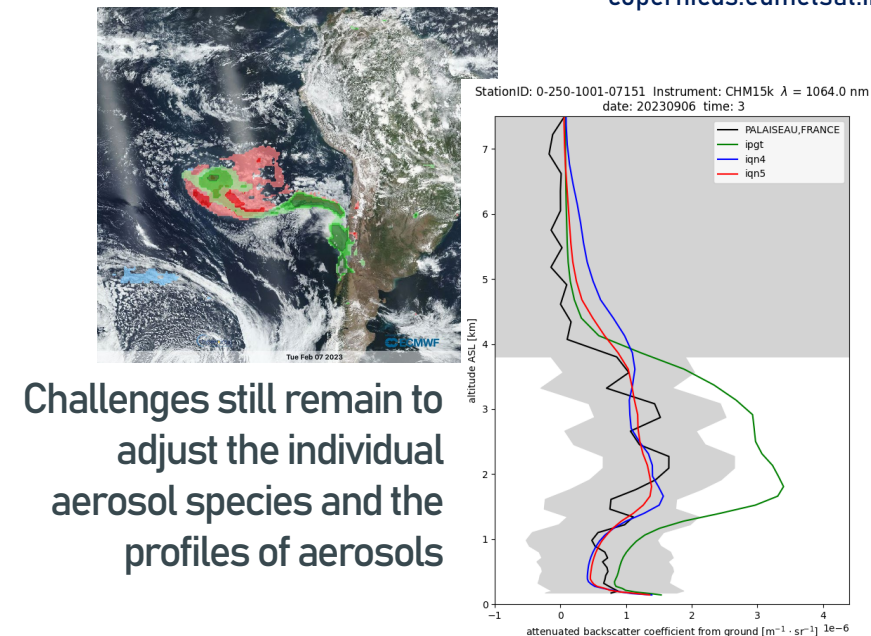
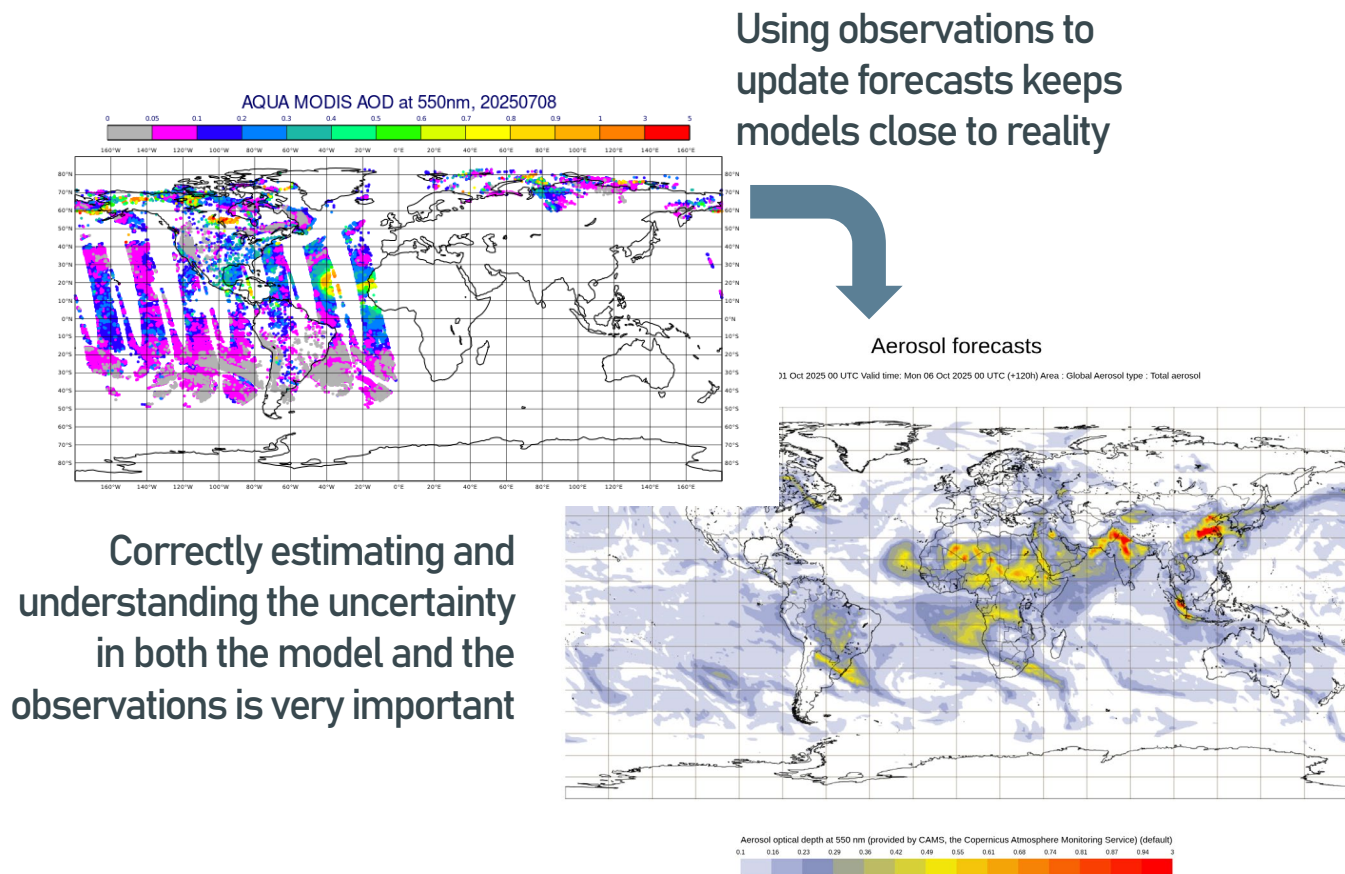
Aerosol forecasts

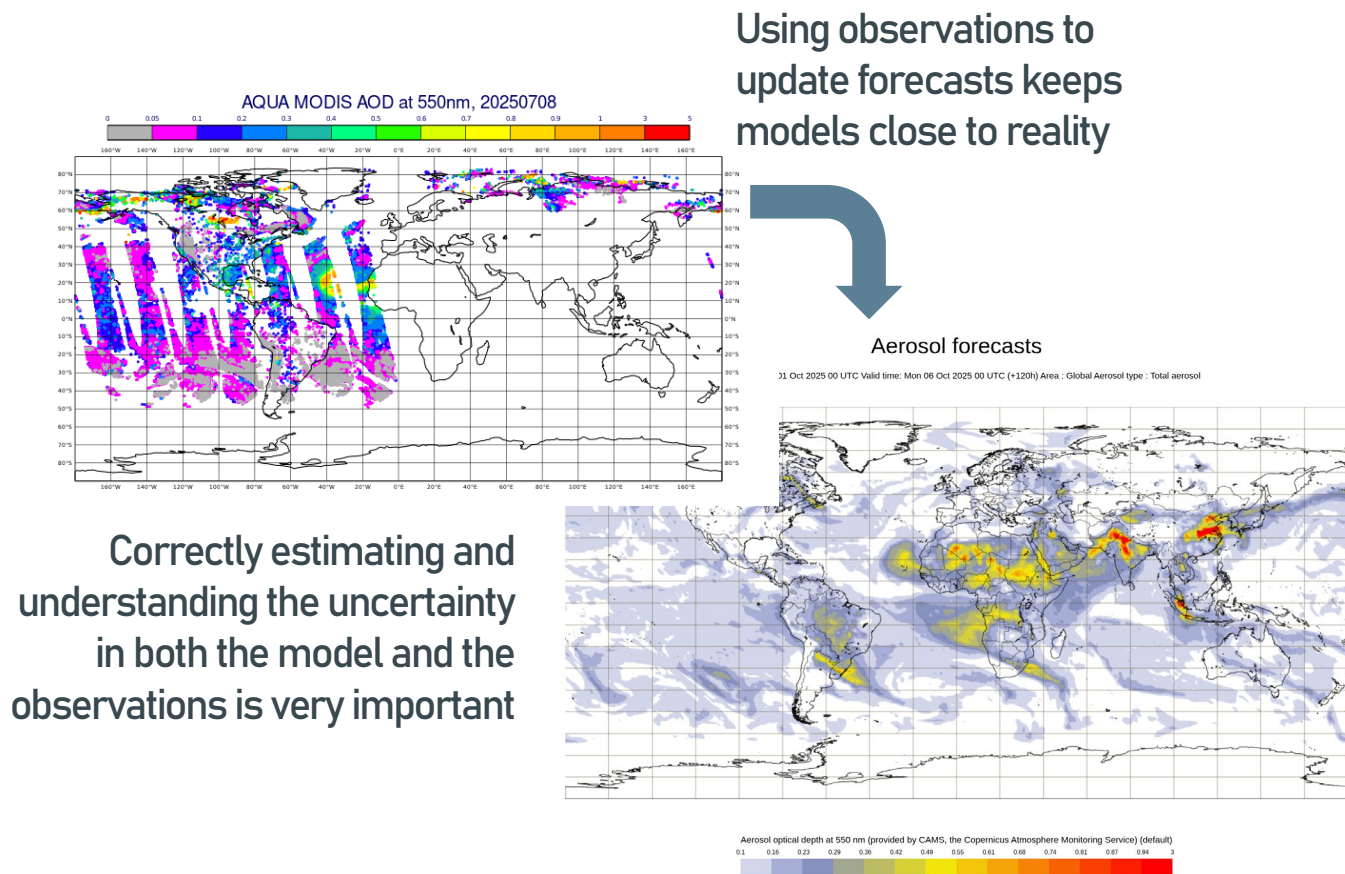
31 Oct 2025 00 UTC Valid time: Mon 06 Oct 2025 00 UTC (+120h) Area : Global Aerosol type : Total aerosol



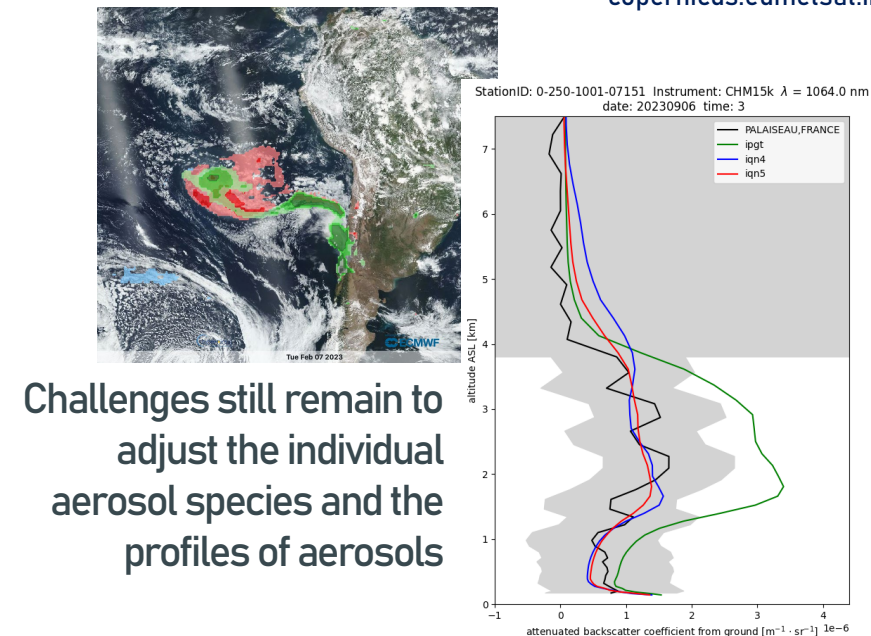
Aerosol optical depth at 550 nm (provided by CAMS, the Copernicus Atmosphere Monitoring Service) (default)

Correctly estimating and
understanding the uncertainty
in both the model and the
observations is very important



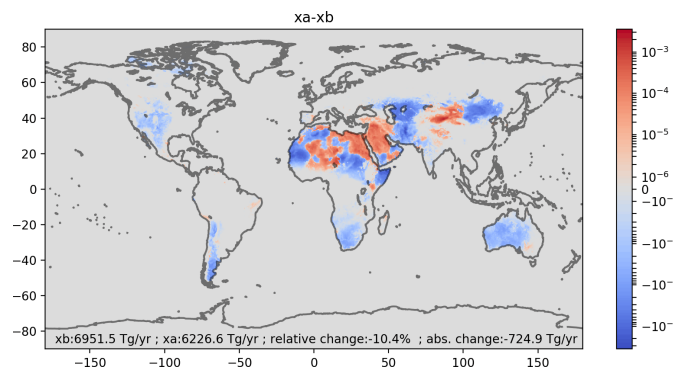


Correctly estimating and understanding the uncertainty in both the model and the observations is very important



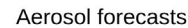
Challenges still remain to adjust the individual aerosol species and the profiles of aerosols

There is the potential to improve emissions as well as initial conditions through observations

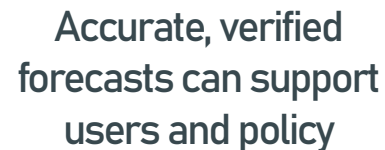
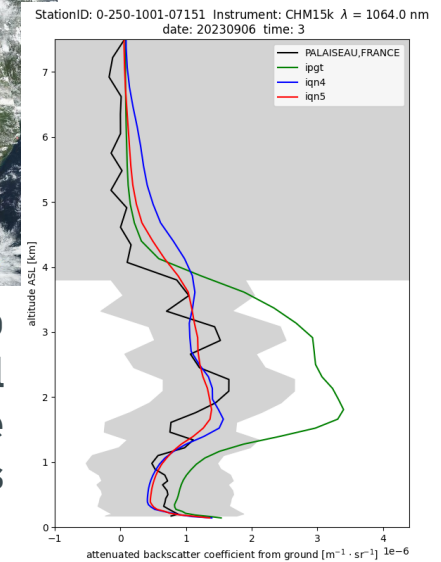
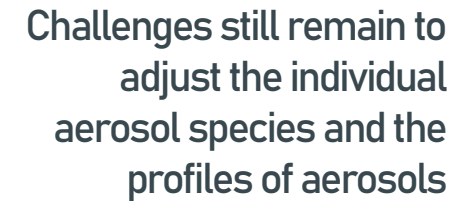
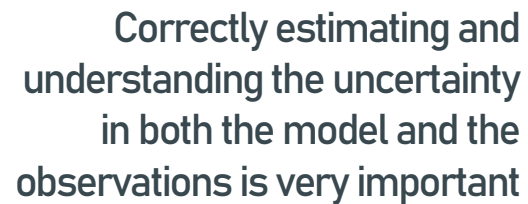




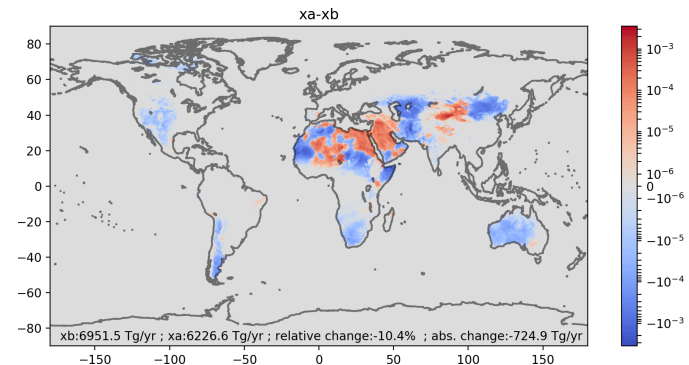
Using observations to update forecasts keeps models close to reality



31 Oct 2025 00 UTC Valid time: Mon 06 Oct 2025 00 UTC (+120h) Area : Global Aerosol type : Total aerosol



There is the potential to improve emissions as well as initial conditions through observations





Thank you!
Questions are welcome.